

Medical procedure assistance based on machine learning

– Current status and future direction

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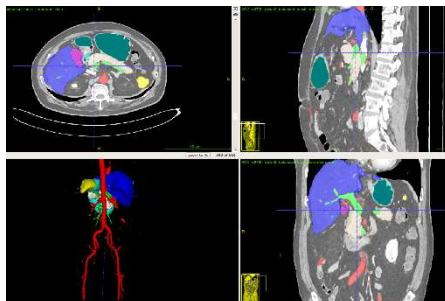
Director of Information Technology Center

Nagoya University



Research topics at Mori Laboratory, Nagoya University

Anatomical structure analysis



Surgical simulation / planning / navigation

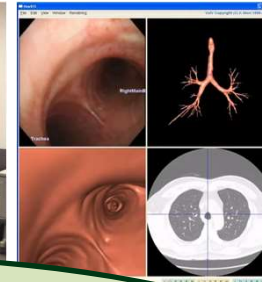


Image analysis

- Image Processing
- Machine learning
- Visualization and VR/AR
- Sensor fusion

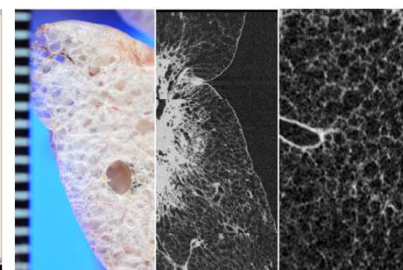
3D Printing



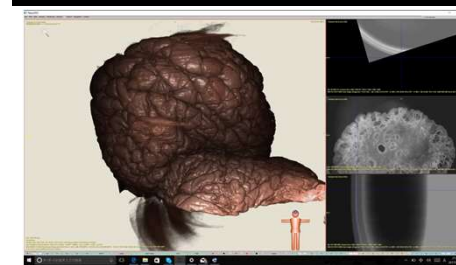
EC-CAD



Micro-structure analysis

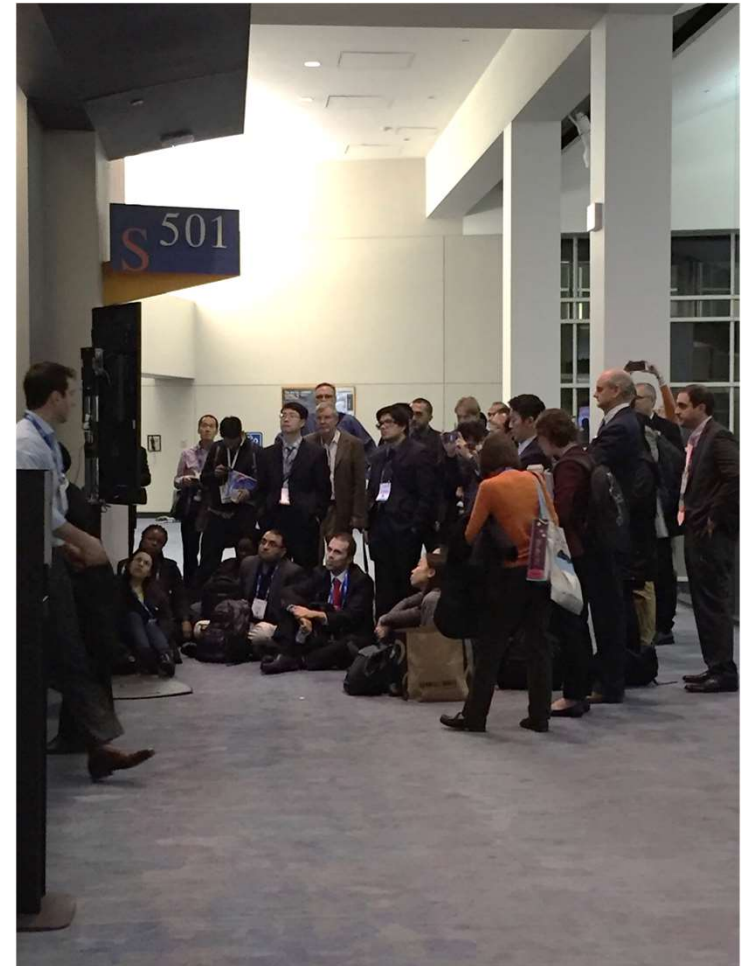


Refraction X-ray

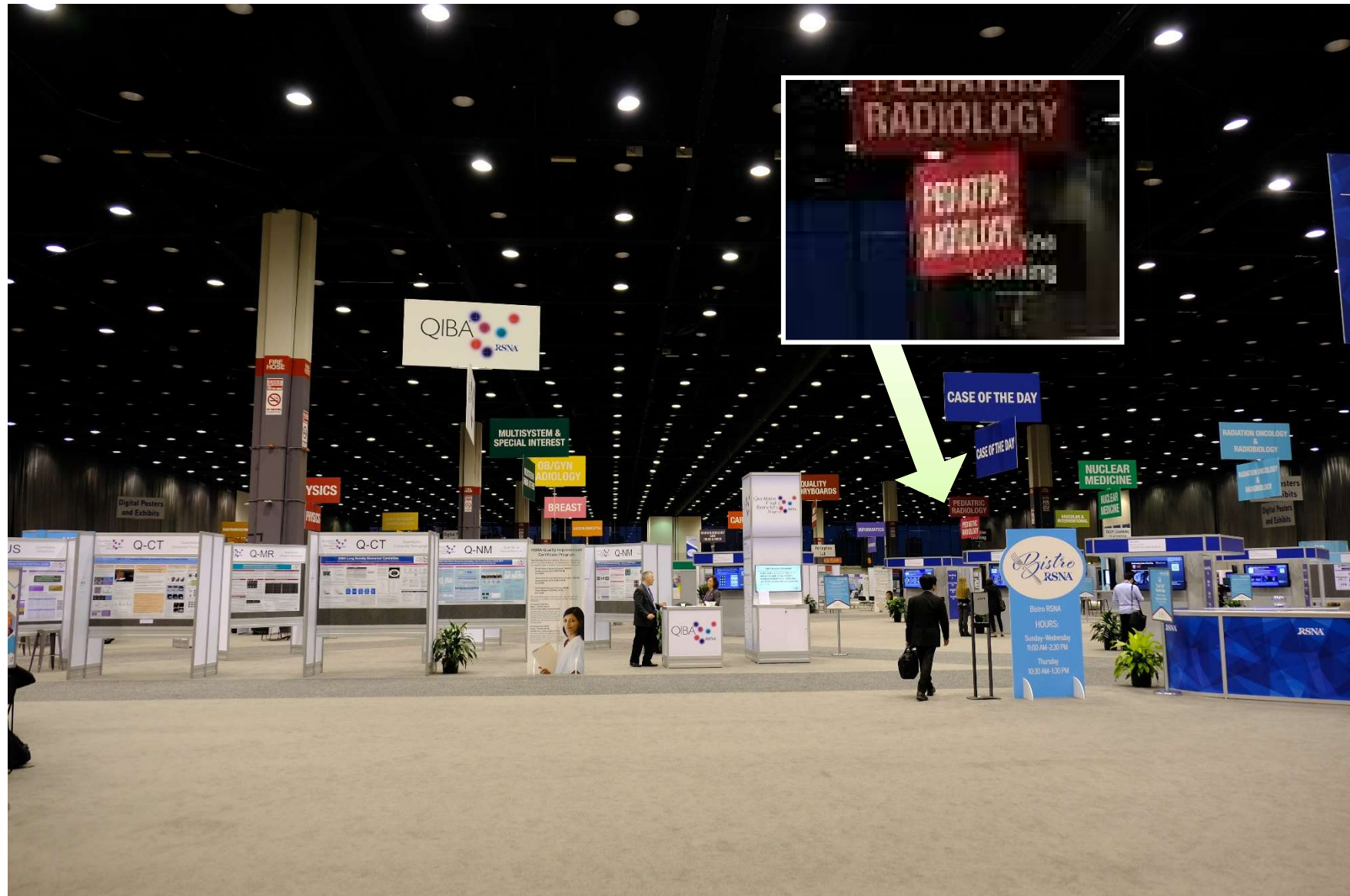


RSNA (Radiological Society of North America)

- 40k – 50k attendees
- ML is big trend in RSNA 2017
- All of ML-related sessions are fully packed

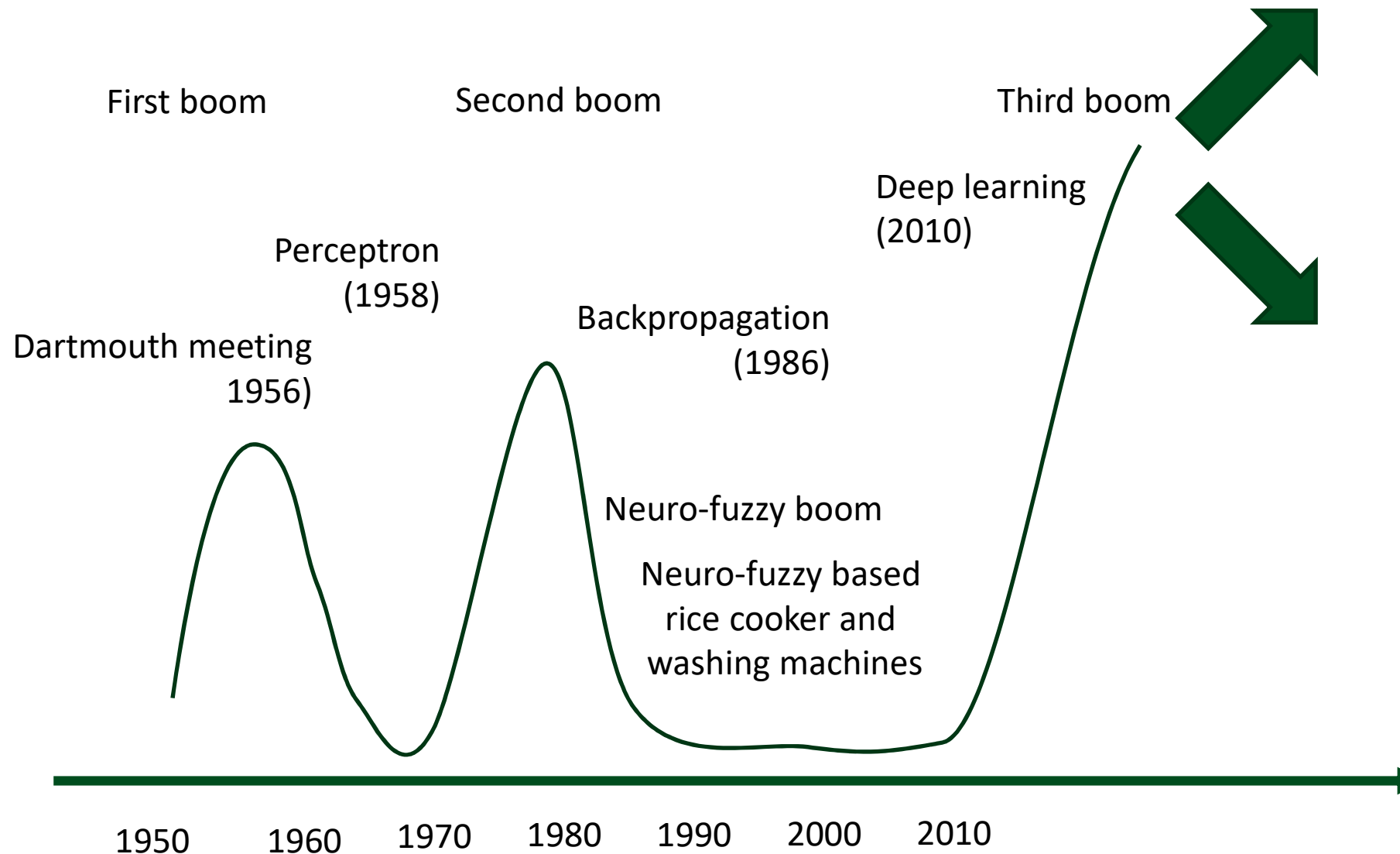


Machine learning is now subspecialty in RSNA



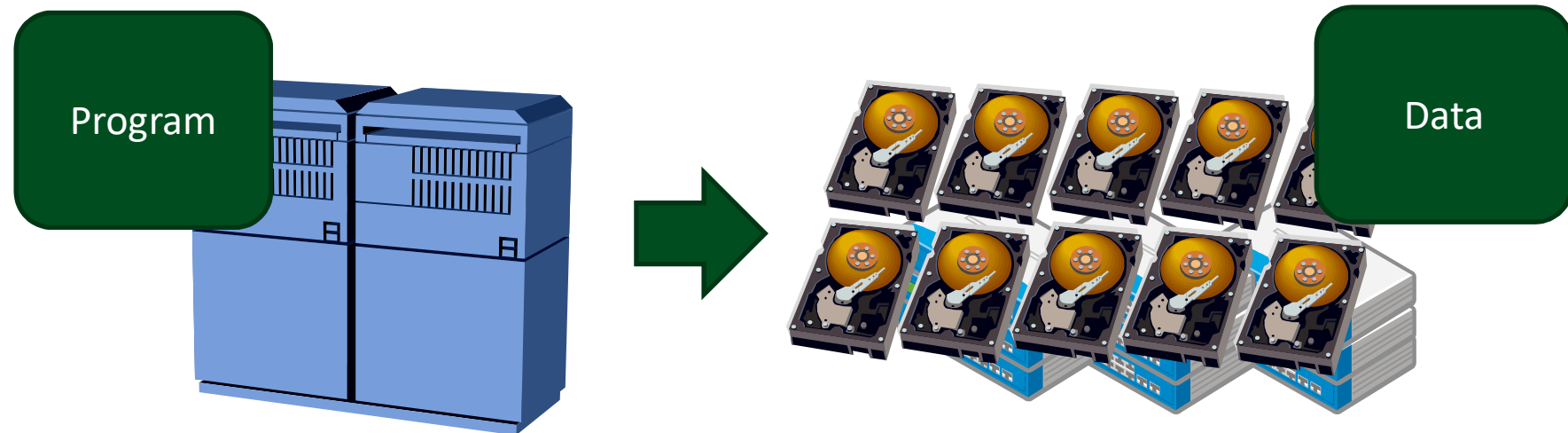


Neural network boom



Trends in information processing

- From Process Driven to Data Driven
 - Reduction of computation and data storage cost
- Data Intensive Computing



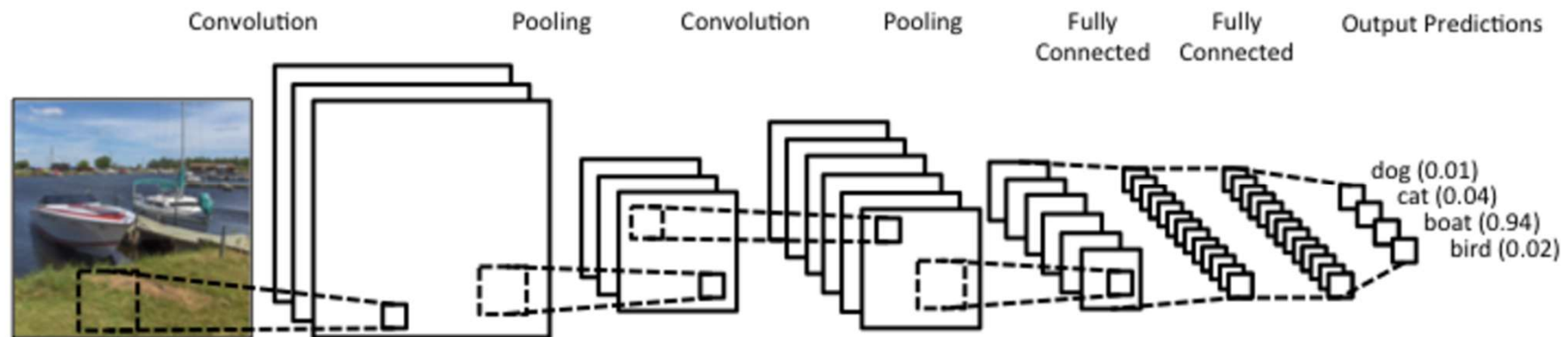
Program is knowledge

Data is knowledge

Everyone is using caffe / tensorflow / chainer
Data is different

Convolutional Neural Network

- Neural network for recognizing images
 - Neocognitron is an origin of CNN [Fukushima]
- Input is image; Output are likelihood of categories
- Convolution layers, maxpooling





All of medical images will be fully annotated by DL in next five years

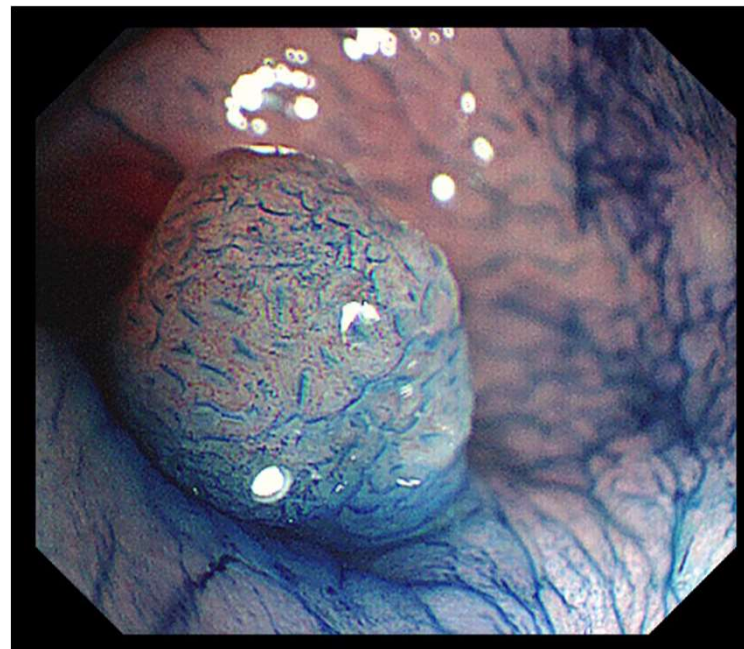


Machine learning in medical system

- Will be used and become very common in many medical fields in next five years?
- Machine intelligence
 - Supporting diagnosis and treatment
 - (Question) autonomous diagnosis and treatment

Endocytoscopy

- Over 500x magnifications
- Real-time observation of cells
- Optical Biopsy



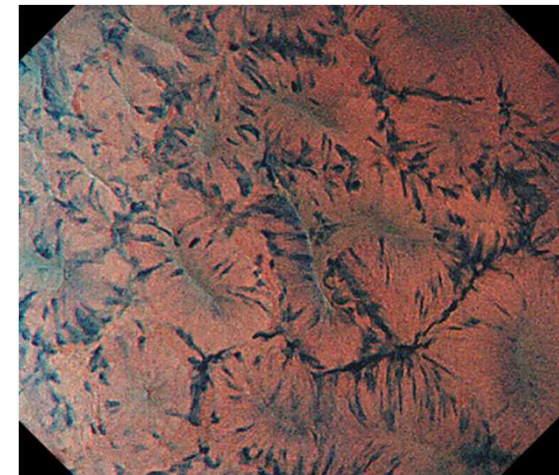
*Inoue H, et al. **Nat Clin Pract Gastroenterol Hepatol** 2005
*Kumagai Y, et al. **Endoscopy** 2004
*Fujishiro M, et al. **Gastrointest Endosc** 2007
*Kudo S, et al. **Endoscopy** 2011
*Mori Y, et al. **Endoscopy** 2013
*Kudo T, et al. **DEN** 2015

New medical device and ML

- Medical devices advance continuously
- More skills are needed to use them and diagnose information obtained from them
- Advanced medical systems should have more intelligence for supporting doctors

Colorectal cancer

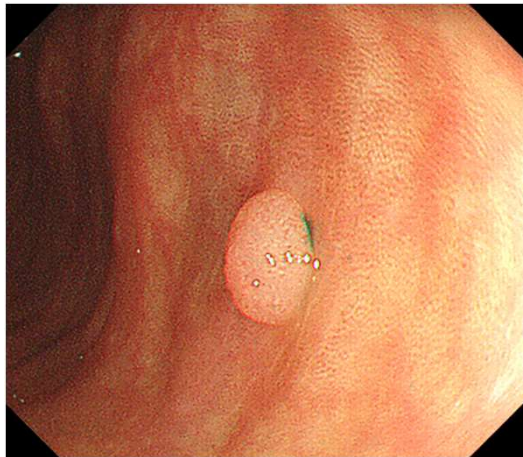
- Colorectal cancer
 - No. 1 cancer in Japan
 - Possible to completely cure for early stage cancers
 - Necessary for early diagnosis and treatment by endoscopy
 - Lack of colorectal endoscopist and pathologist
- Endocytoscopy
 - New endoscope
 - 380x – 500x magnification
 - Cell-level observation
 - Optical biopsy



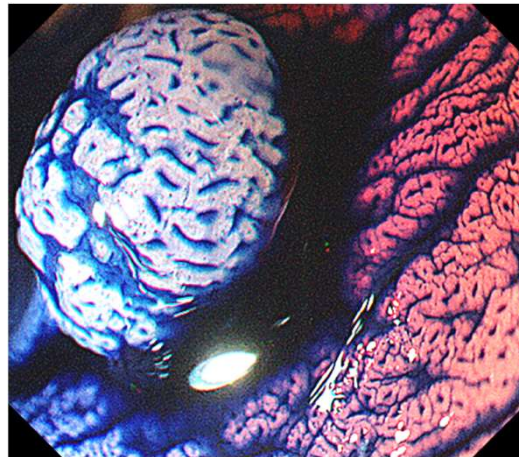
Endocytoscopic image

Classification of tumor or non-tumor

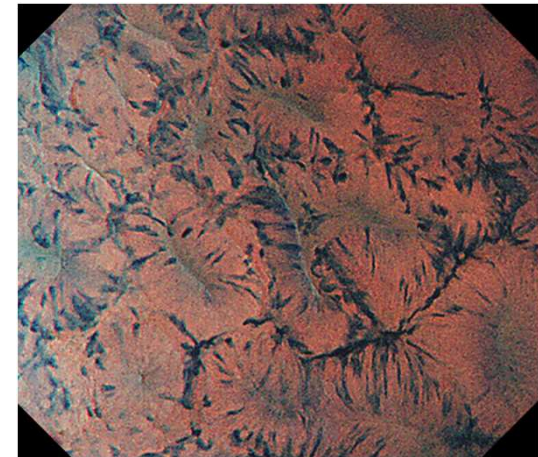
- Conventional colonoscope
 - 70-80% accuracy
- Endocytoscopy
 - Accuracy: >90% (experts), 80% (non expert)
 - Long time training for achieve high-accuracy diagnosis



Colonoscopic image



Magnified colonoscopic image

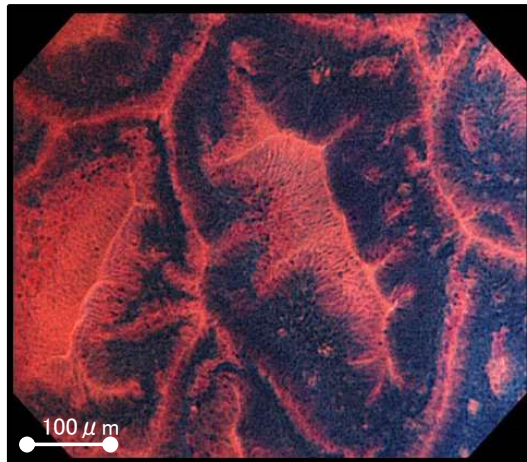


Endocytoscopic image

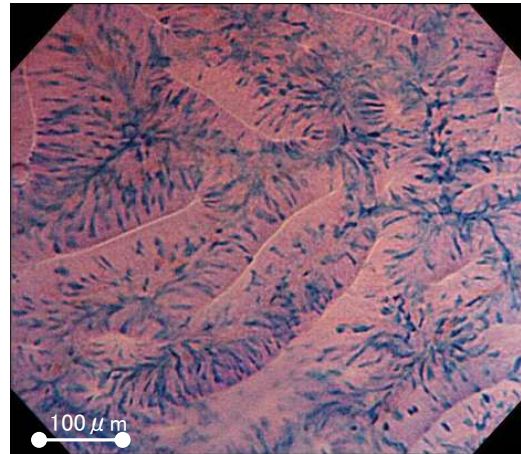
Similarity between EC images and HE images

EC

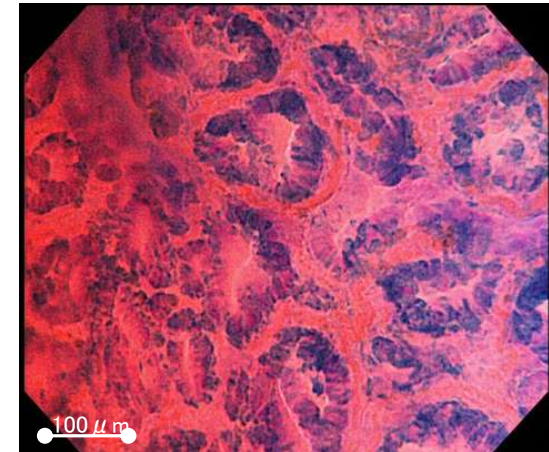
Hyperplastic polyp



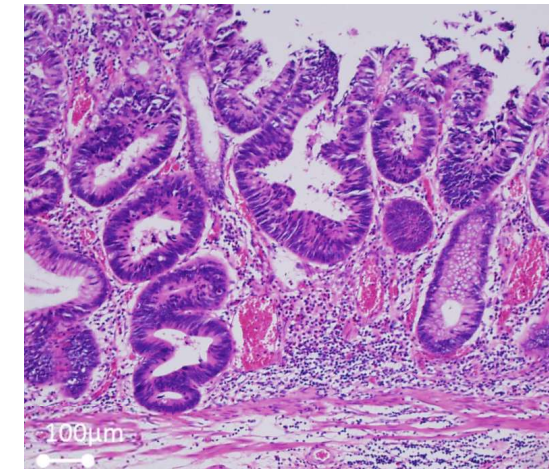
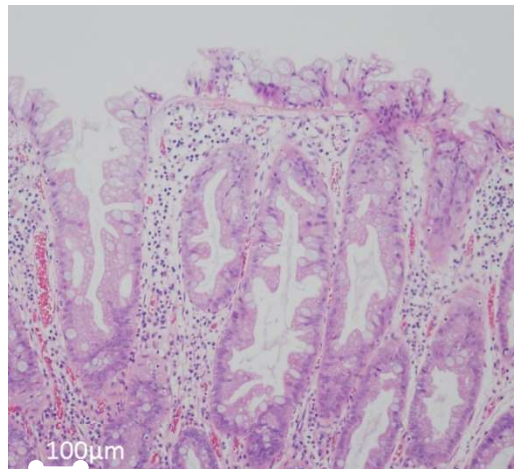
Adenoma



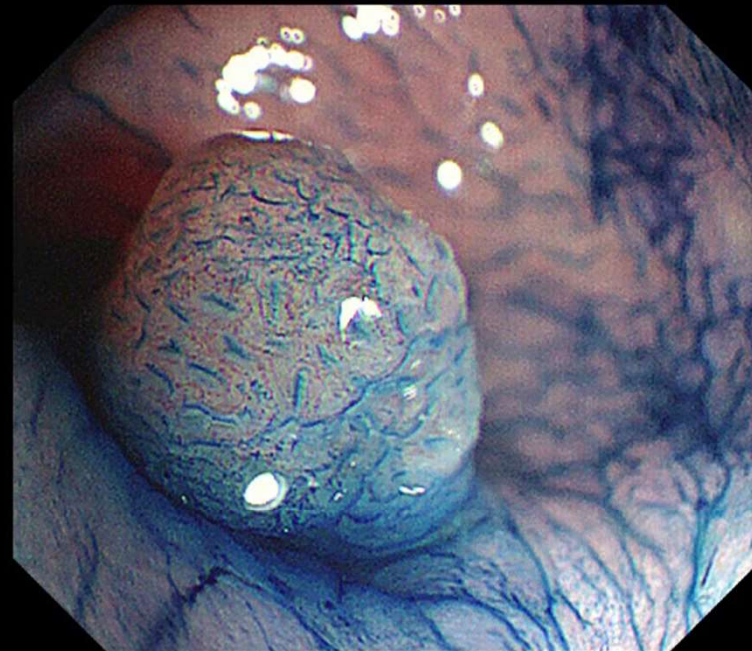
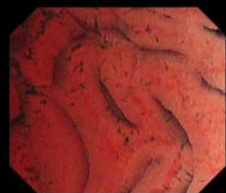
Cancer



Pathology

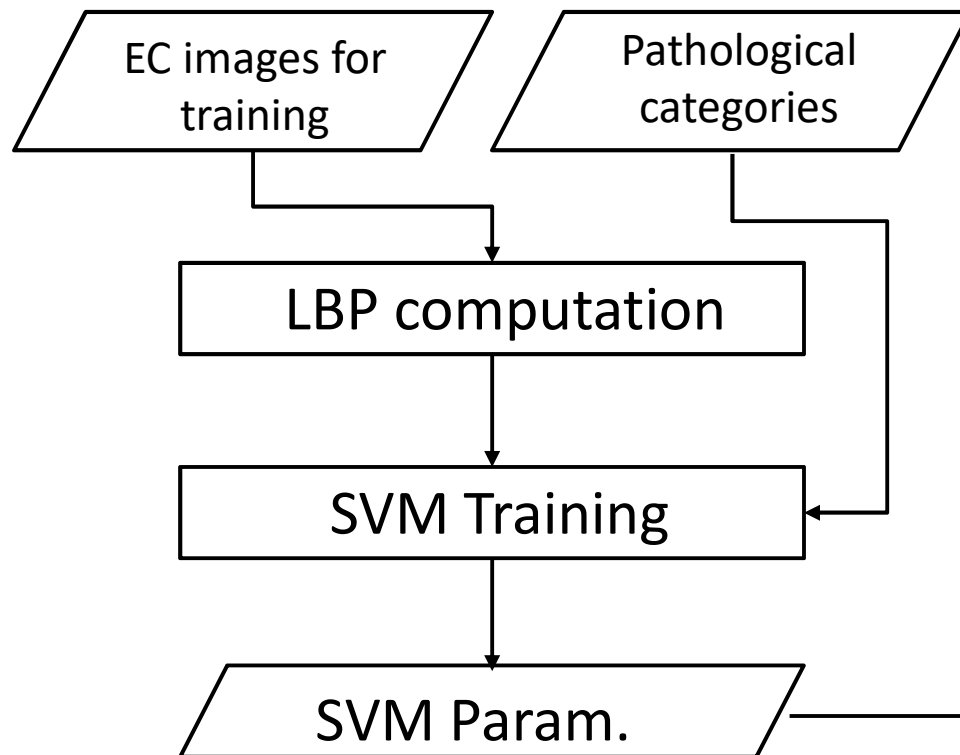


Automated endocytoscopic video analysis

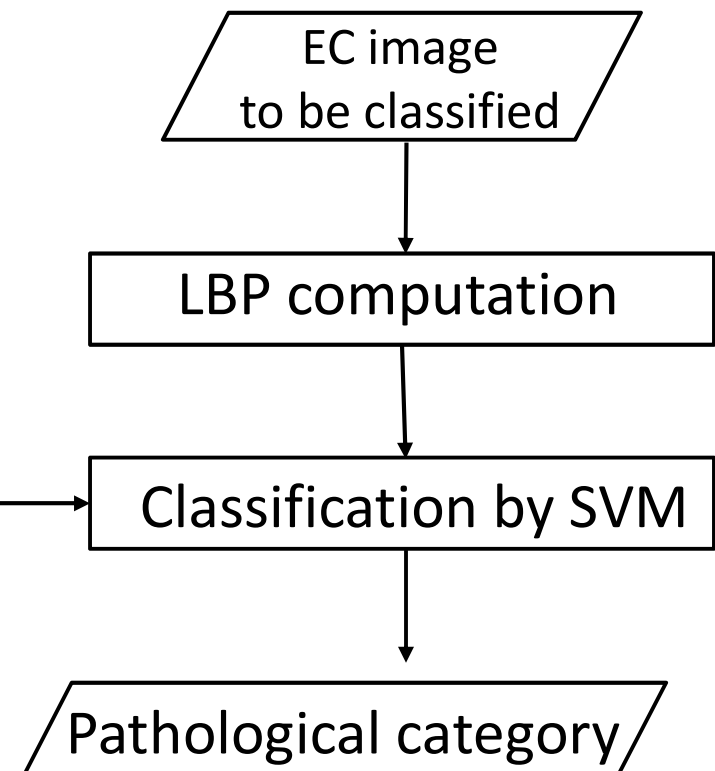


Processing flow

Training

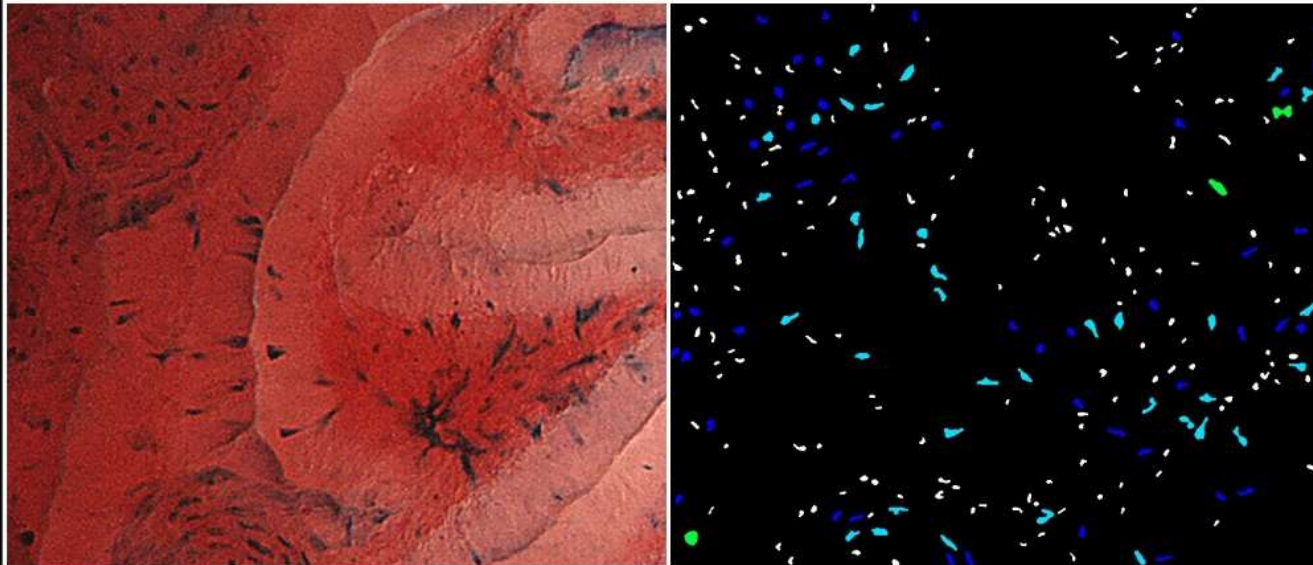


Testing



Output images

Adenoma



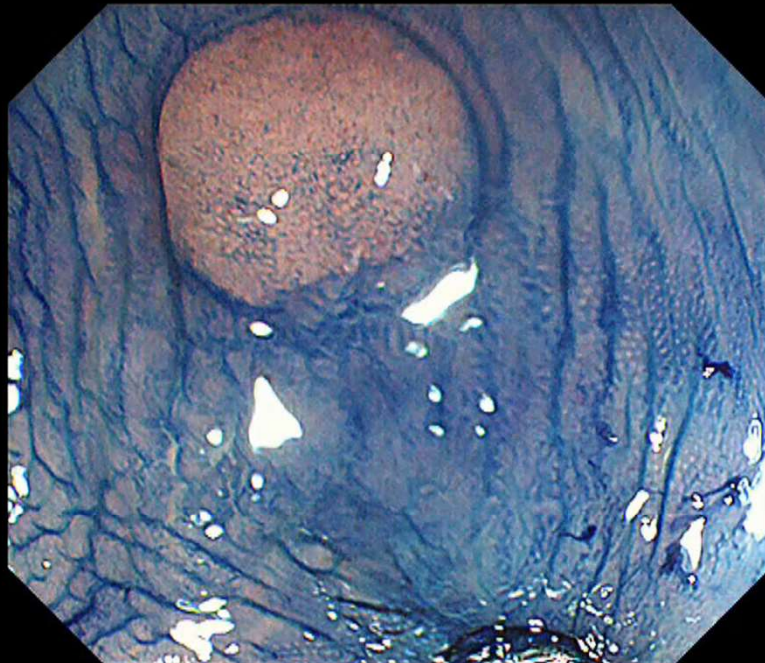
HIGH CONFIDENCE

Probability: **99** %

if confidential probability is over 90% we output "High confidence"

Diagnostic probability

Next, VIDEO



Endo BRAIN



1110

Original article

Impact of an automated system for endoscopic diagnosis of small colorectal lesions: an international web-based study

Authors

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Institutions

Institutions are listed at end of article.

submitted

28. February 2016

accepted after revision

4. July 2016

Background and study aims: Optical diagnosis of colorectal polyps is expected to improve the cost-effectiveness of colonoscopy, but achieving a high accuracy is difficult for trainees. Computer-aided diagnosis (CAD) is therefore receiving at-

for high confidence optical diagnoses of diminutive polyps.

Results: Of the 205 small polyps (147 neoplastic and 58 non-neoplastic), 139 were diminutive. CAD was accurate for 89% (95% confidence inter-

Mori et al., "Impact of an automated system for endoscopic diagnosis of small colorectal lesions: an international web-based study," *Endoscopy*, 48, 2016

EC-CAD v.s. Experts or Non-experts ($\geq 5\text{mm}$)

Table 2 Diagnostic performance of the computer-aided diagnosis system for endocytoscopic imaging (EC-CAD), the experts, and the non-experts for the 139 diminutive ($\leq 5\text{ mm}$) lesions.

	EC-CAD		Experts (N=3)		Non-experts (N=10)		P value	
	n/n	% (95%CI)	n/n	% (95%CI)	n/n	% (95%CI)	EC-CAD vs. experts	EC-CAD vs. non-experts
Sensitivity	80/91	88 (79 – 94)	248/273	91 (87 – 94)	646/910	71 (68 – 74)	0.256 ¹	<0.001 ¹
Specificity	44/48	92 (80 – 98)	128/144	89 (83 – 94)	374/480	78 (74 – 82)	0.540 ¹	<0.001 ¹
Accuracy	124/139	89 (83 – 94)	376/417	90 (87 – 93)	1020/1390	73 (71 – 76)	0.703 ¹	<0.001 ¹
PPV	80/81	99 (93 – 100)	248/264	94 (90 – 96)	646/752	86 (83 – 88)	0.137 ²	<0.001 ²
NPV	44/52	85 (72 – 93)	128/153	84 (77 – 89)	374/638	59 (55 – 62)	0.871 ³	<0.001 ³
Rate of high confidence diagnosis	113/139	81 (74 – 87)	327/417	78 (74 – 82)	1117/1390	80 (78 – 82)	0.470 ³	0.791 ³
NPV when diagnosing all polyps with high confidence	43/46	93 (82 – 99)	115/125	92 (86 – 96)	319/487	66 (61 – 70)	1.000 ²	<0.001 ²
NPV when diagnosing rectosigmoid polyps with high confidence	34/35	97 (85 – 100)	97/98	99 (94 – 100)	258/312	83 (78 – 87)	0.459 ²	0.026 ²
Average time for diagnosis (95%CI), seconds		0.2 (0.2 – 0.2)		10 (9 – 10)		15 (14 – 15)	<0.001 ⁴	<0.001 ⁴

CI, confidence interval; PPV, positive predictive value; NPV, negative predictive value.

¹ McNemar test.

² Fisher's exact test.

³ Chi-squared test.

⁴ Kruskal –Wallis one-way analysis of variance

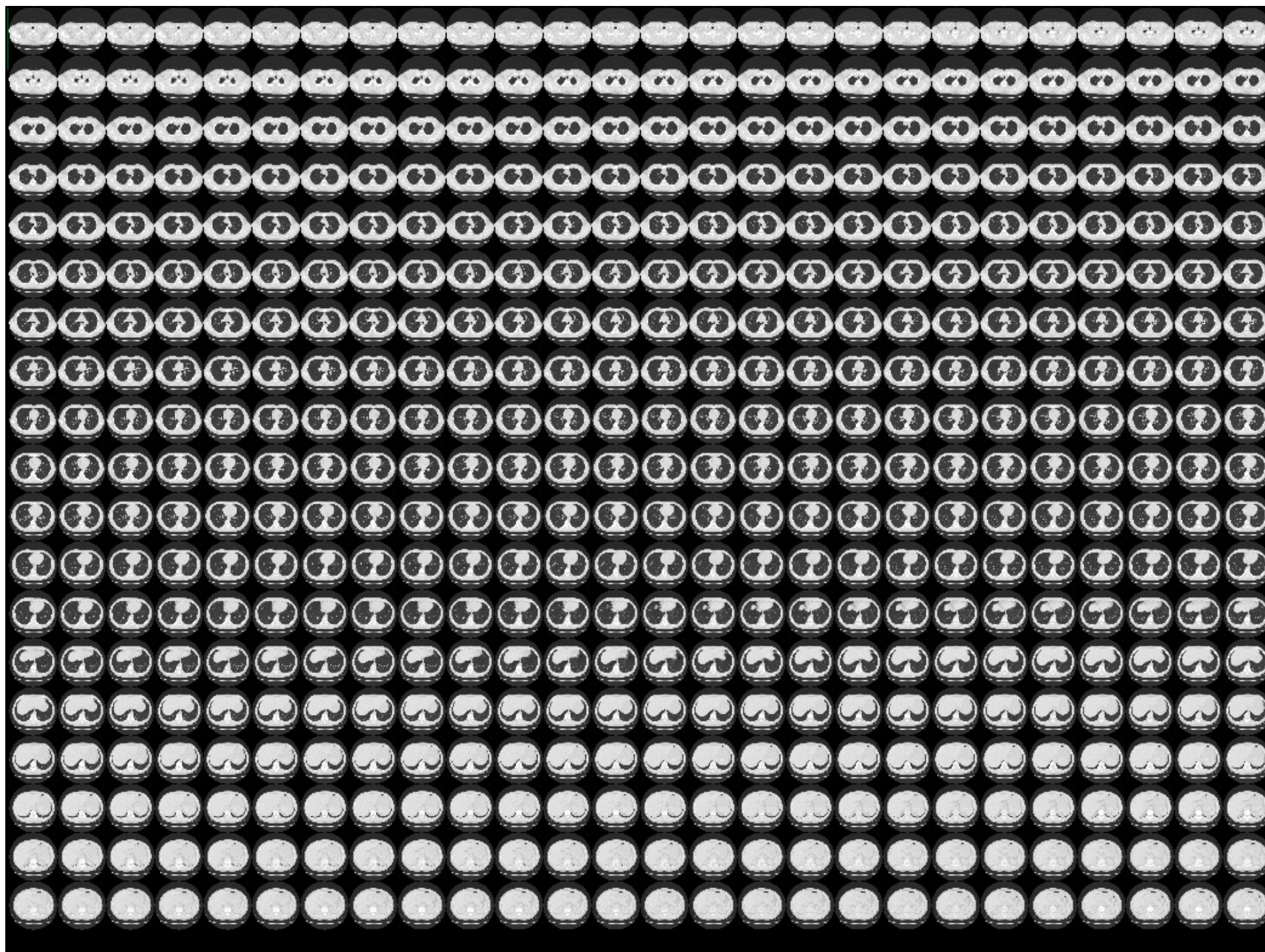
no significant difference significant difference

Experts (90%) > EC-CAD (89%) >> Non-experts (73%)

Mori et al., “Impact of an automated system for endocytoscopic diagnosis of small colorectal lesions: an international web-based study,” Endoscopy, 48, 2016

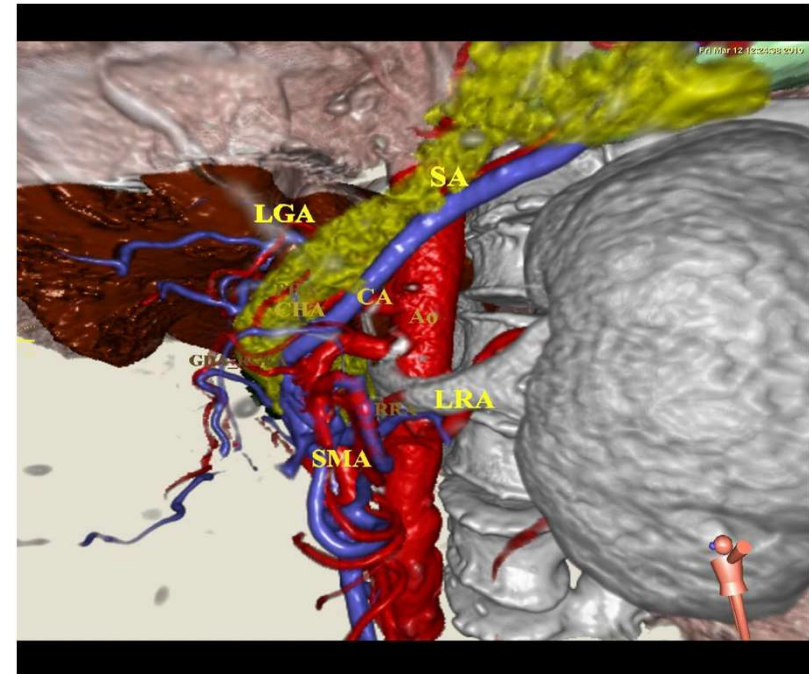
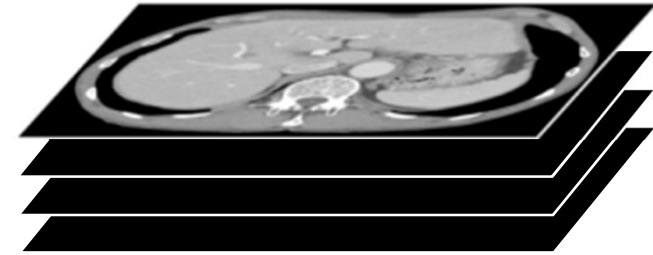


Colonic polyps detection from colonoscopic videos



Important information for surgical navigation

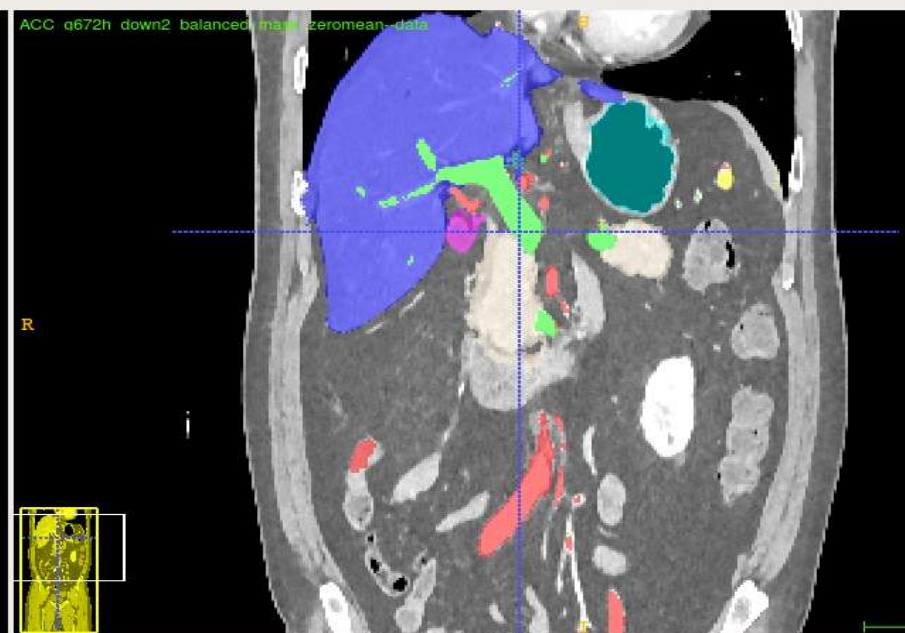
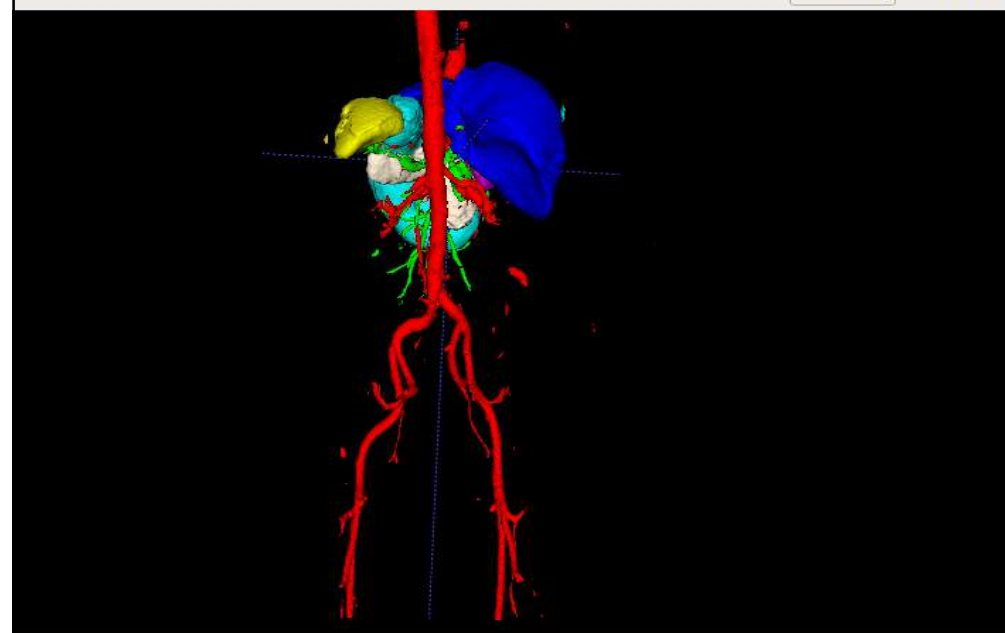
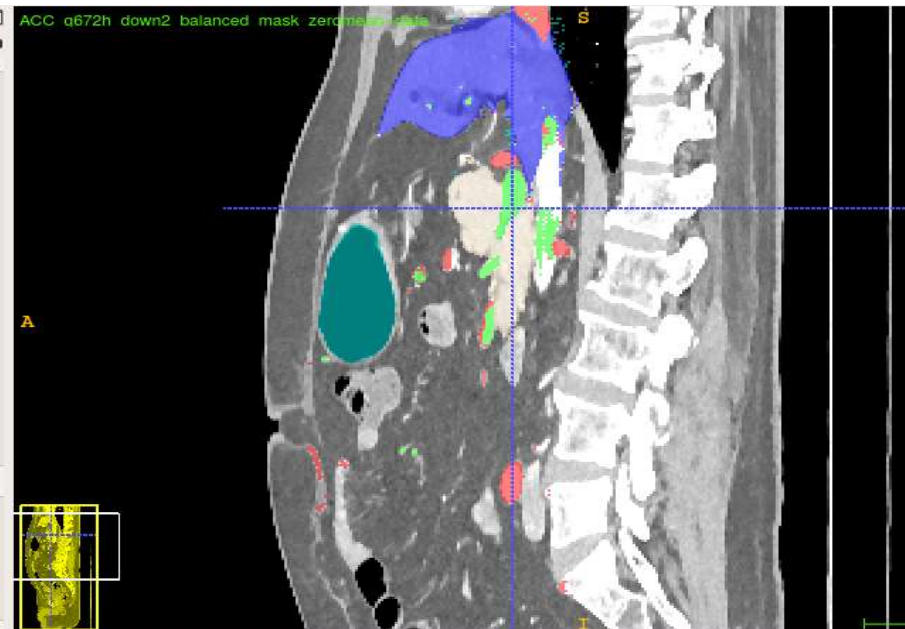
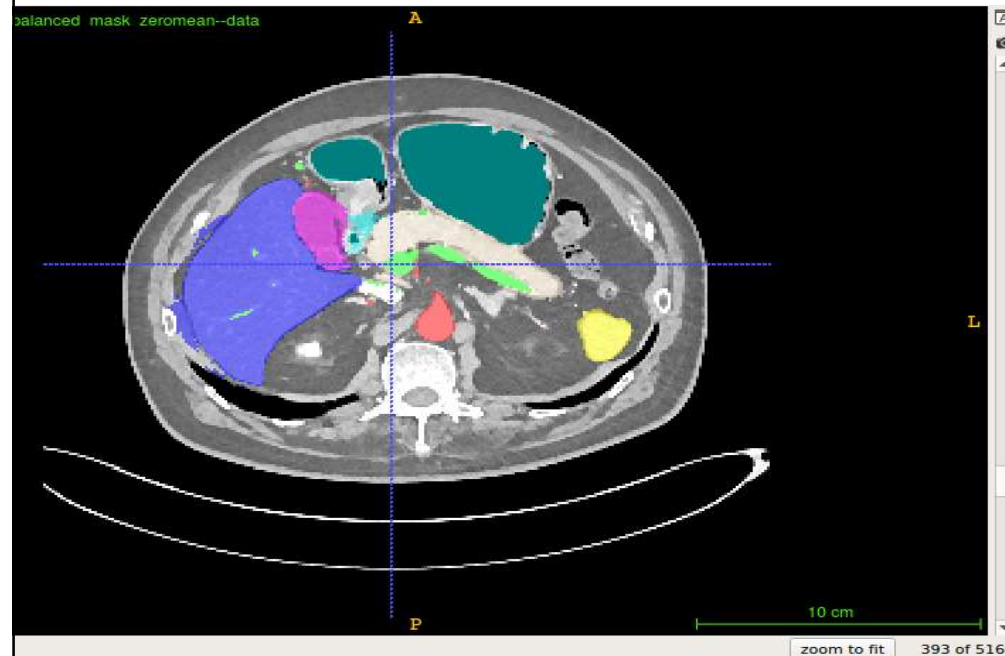
- Tracking information
- Anatomical structure information
- Anatomical name information
- Anatomical variation information





Imperial College
London

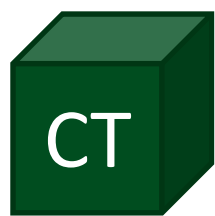
Organ segmentation



Fully convolutional architectures (3D U-Net)

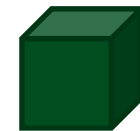
Input:

132x 132x 116 x 1

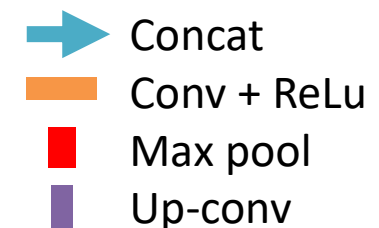
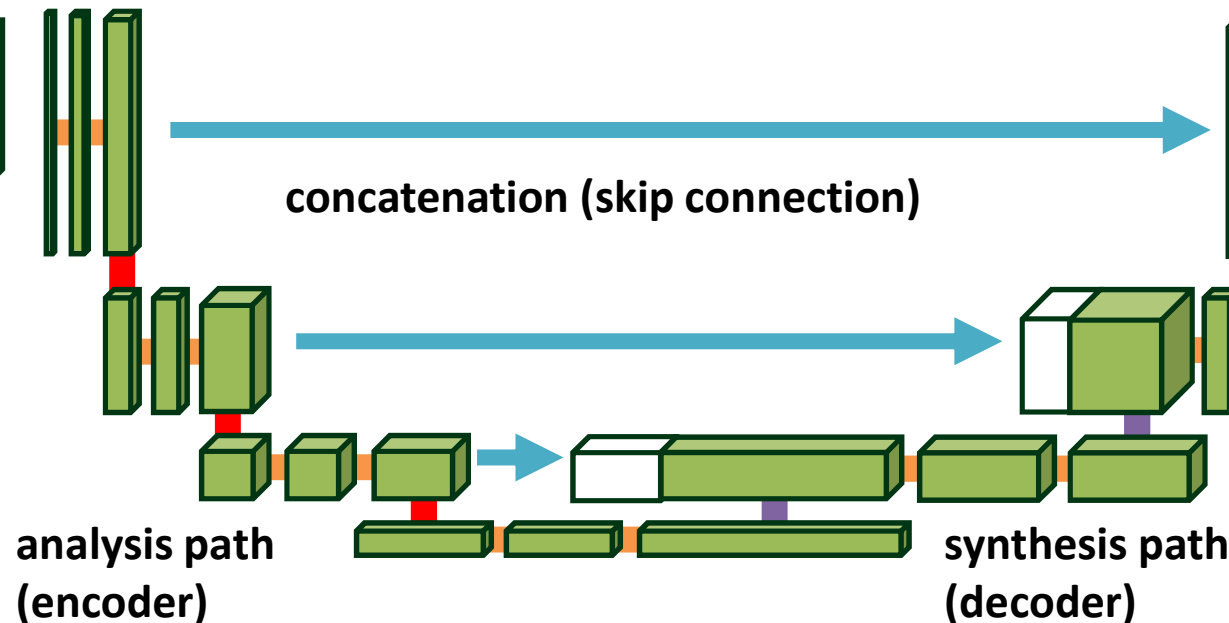


Output:

44 x 44 x 28 x 8



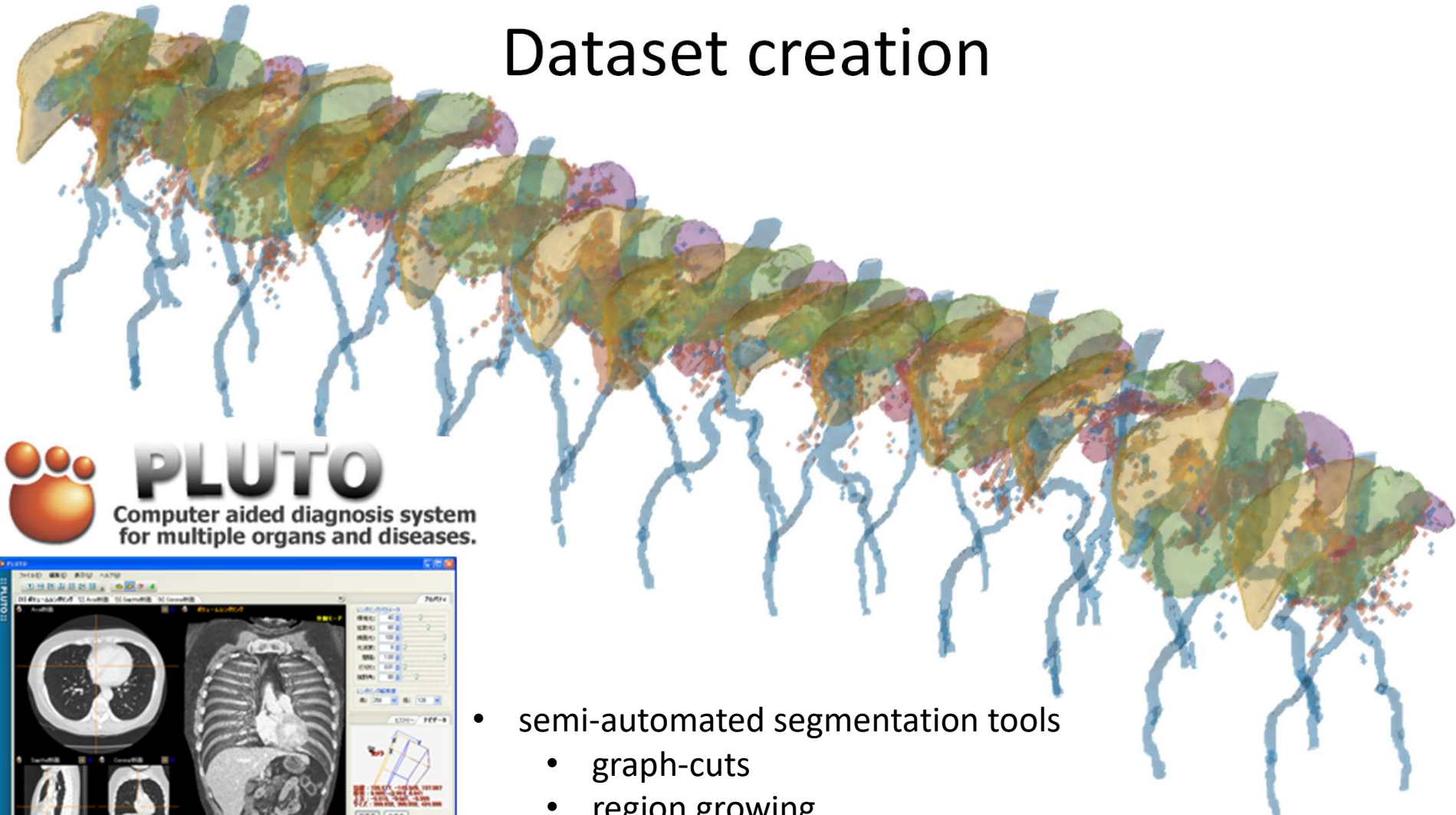
1. background
2. artery
3. vein
4. liver
5. spleen
6. stomach
7. gallbladder
8. pancreas



- Network:
 - Encoder-decoder structure
 - concatenation (skip) connections to preserve detail in the result
- No fully connected layers as in standard classification CNN
- 19 million learnable parameters
- Fits on one 12GB GPU (NVIDIA TITAN X) for training
- Implementation in *Caffe*

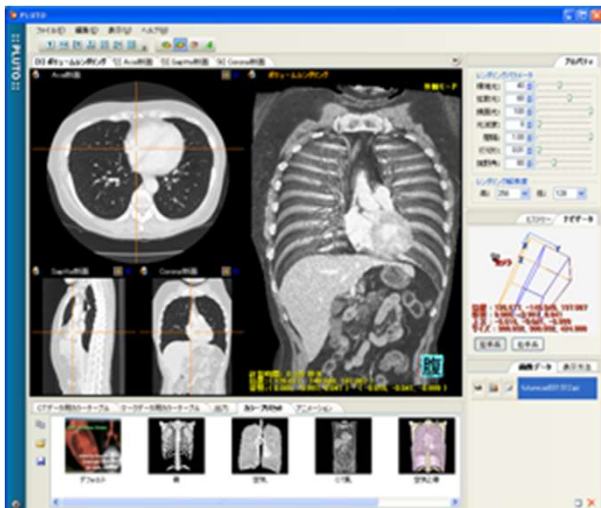
Figure after 3D U-Net [Çiçek et al. MICCAI 2016]

Dataset creation



PLUTO

Computer aided diagnosis system
for multiple organs and diseases.

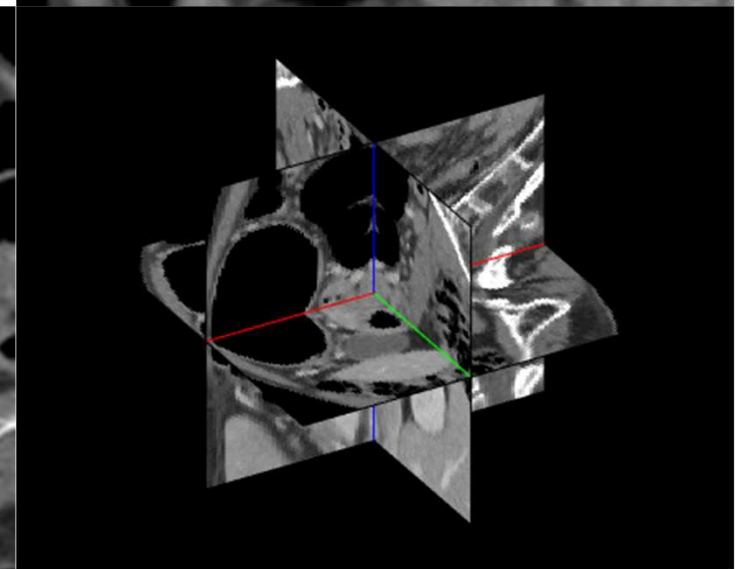
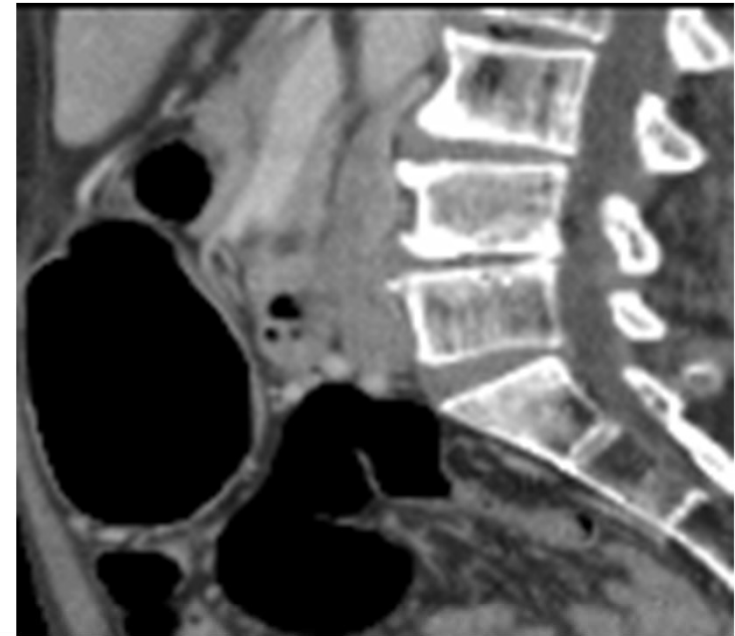


- semi-automated segmentation tools
 - graph-cuts
 - region growing
- data collected from 2009~2017 (330 cases)

<http://pluto.newves.org>

Data augmentation

- random cropping
- random rotations
- elastic B-spline deformations



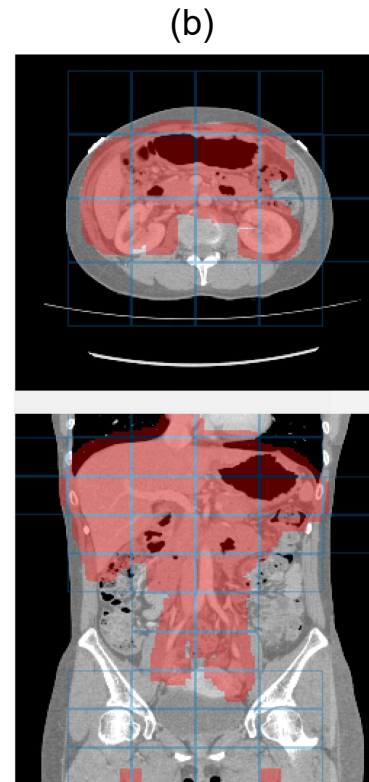
'CreateDeformation'
and
'ApplyDeformation'
layers

3D U-Net [Cicek et al. MICCAI 2016]

Ground truth



Stage 2 – Tiling



Stage 2 result



Example of the validation set with

(a) ground truth and illustrating

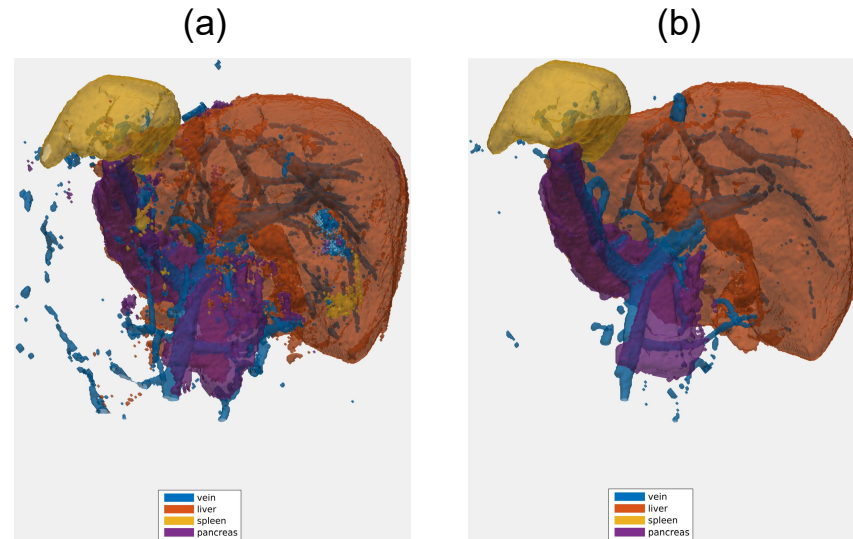
(b) Tiling approach on 2nd stage candidate region, Resulting segmentation is shown in (c).

Note that the grid shows the output tiles of size $44 \times 44 \times 28$ (x,y,z-directions). Each predicted tile is based on a larger input of $132 \times 132 \times 116$ that the network processes as defined by GPU requirements (12 GB)

[H. Roth et al. arXiv 1704.06382](https://arxiv.org/abs/1704.06382)

Test on **unseen** dataset

[H. Roth et al. arXiv 1704.06382](https://arxiv.org/abs/1704.06382)



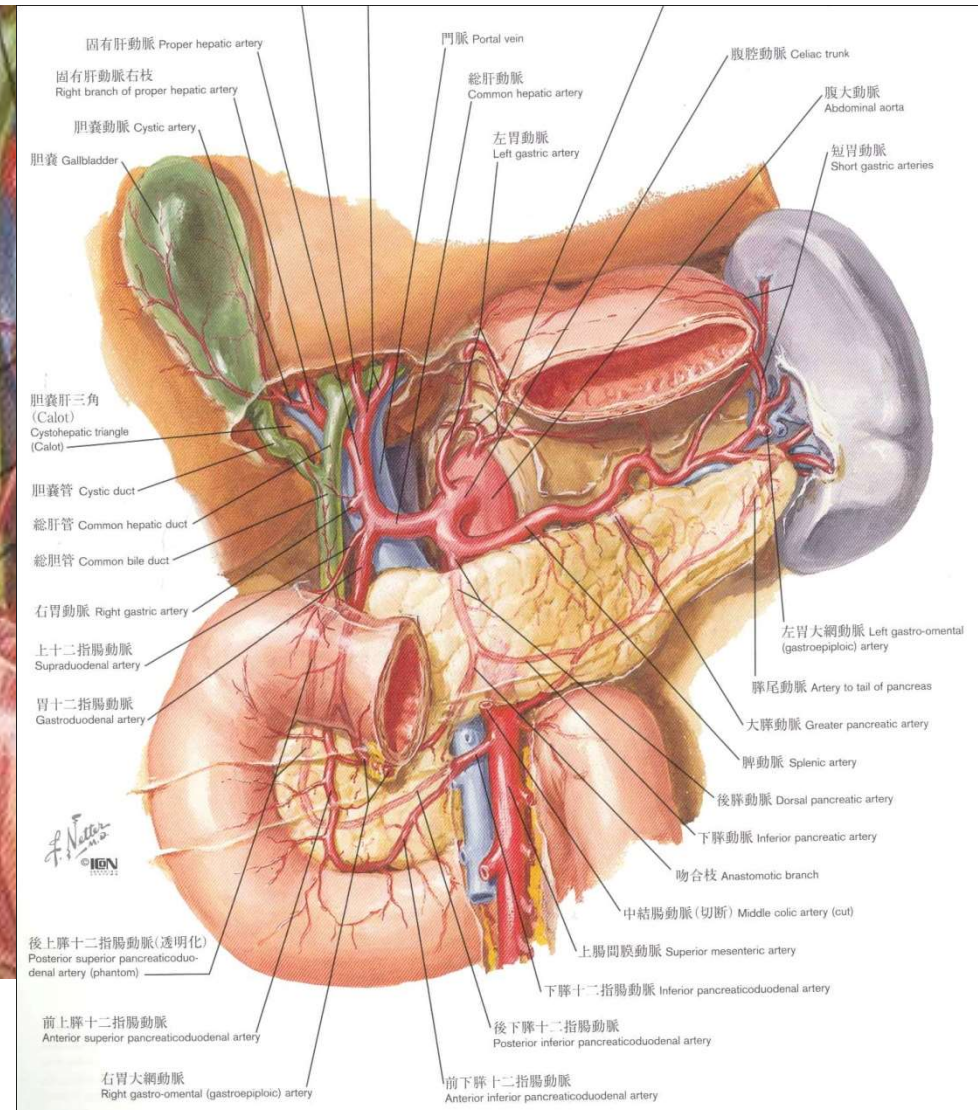
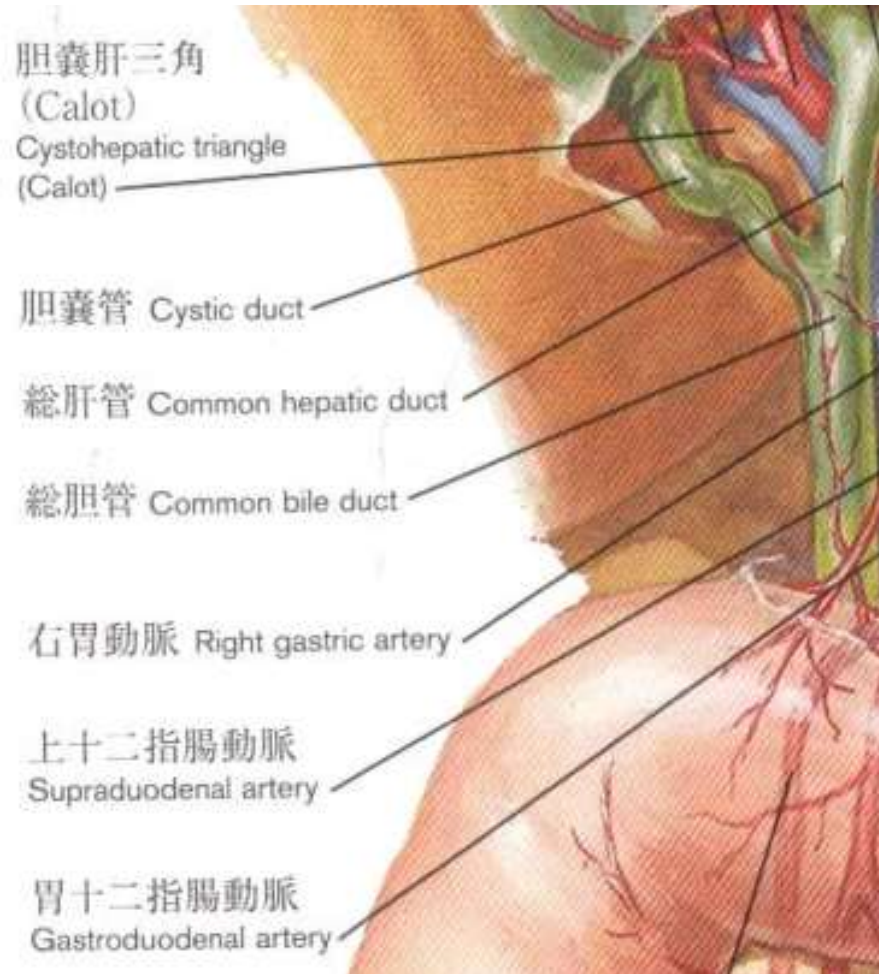
Surface renderings: (a) result of proposed method in first stage and (c) the second-stage results using and overlapping (OL) tiles strategy.

Table 2: **Testing on unseen dataset:** Dice similarity score [%] of different stages of FCN processing.

	Stage 1: Non-overlapping			Stage 2: non-overlapping			Stage 2: Overlapping		
Dice	liver	spleen	pancreas	liver	spleen	pancreas	liver	spleen	pancreas
Mean	93.6	89.7	68.5	94.9	91.4	81.2	95.4	92.8	82.2
Std	2.5	8.2	8.2	2.1	8.9	10.2	2.0	8.0	10.2
Median	94.2	91.8	70.3	95.4	94.2	83.1	96.0	95.4	84.5
Min	78.2	20.6	32.0	80.4	22.3	1.9	80.9	21.7	1.8
Max	96.8	95.7	82.3	97.3	97.4	91.3	97.7	98.1	92.2

150 abdominal ceCTs from different hospital and scanner

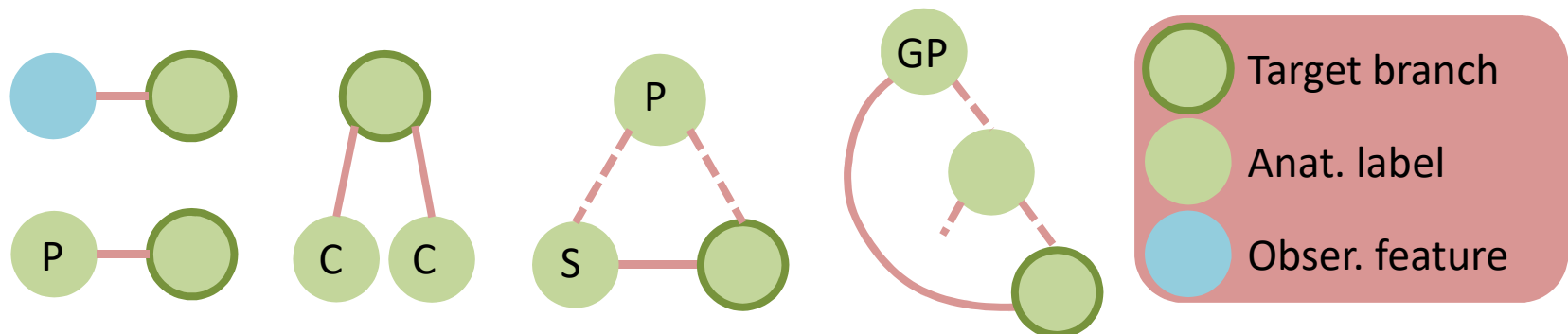
Anatomical name understanding



Anatomical labeling by structure learning

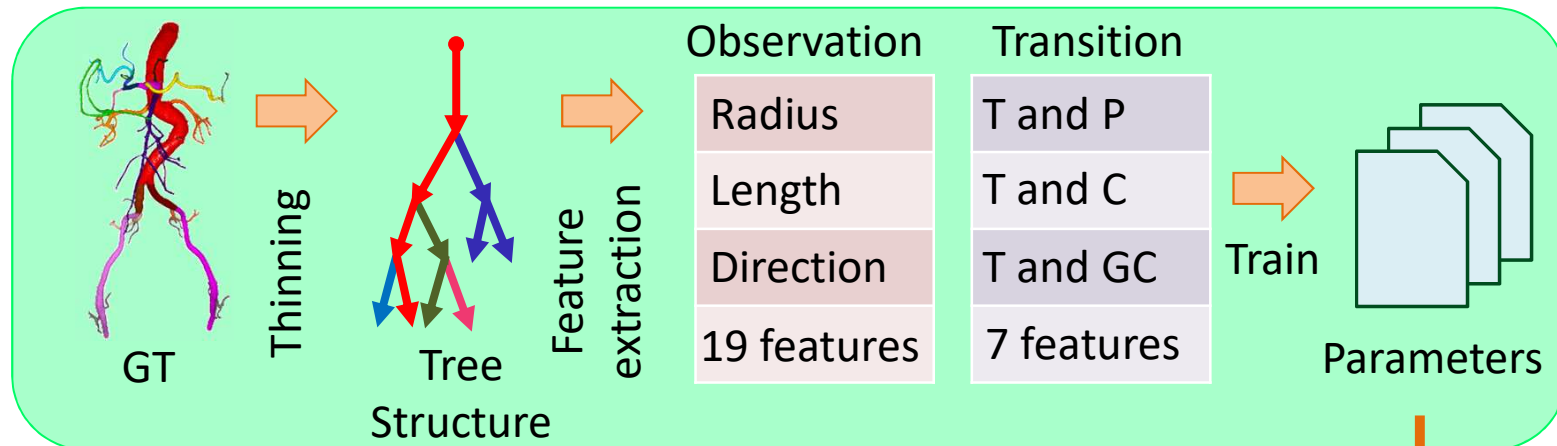
- Structure learning
 - Representation of features and labels
 - Possible to represent global structure of branching pattern
 - Possible to infer optimal blood vessel labels
- Conditional random field
 - Learn observation features and anatomical labels
 - Observation features (19)
 - Transition features (7)
 - Relationship of target branch and other branches

Ex.

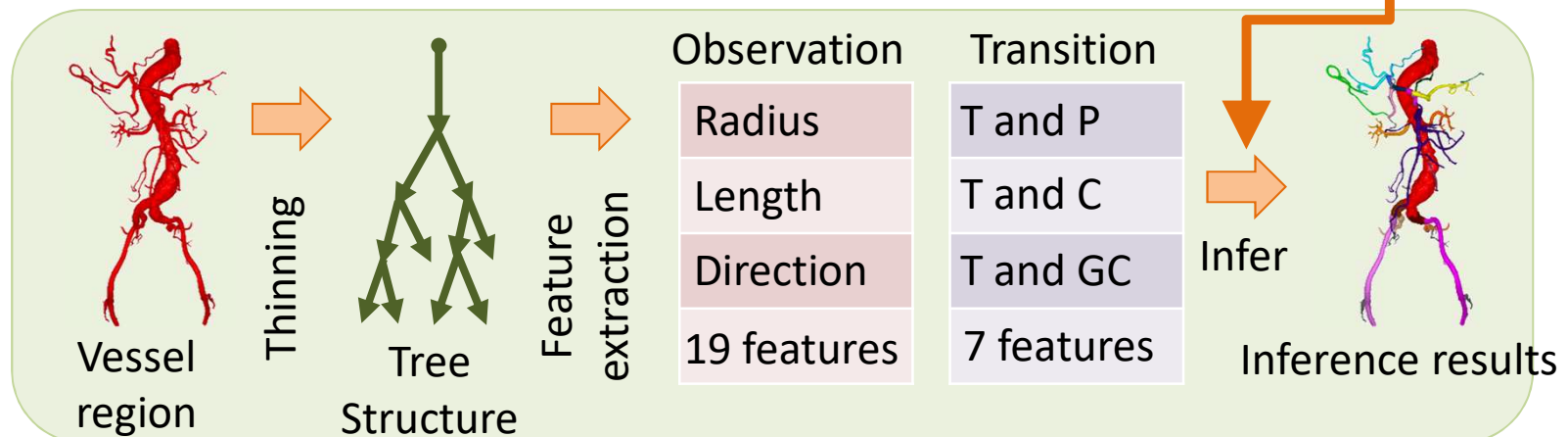


Conditional random field

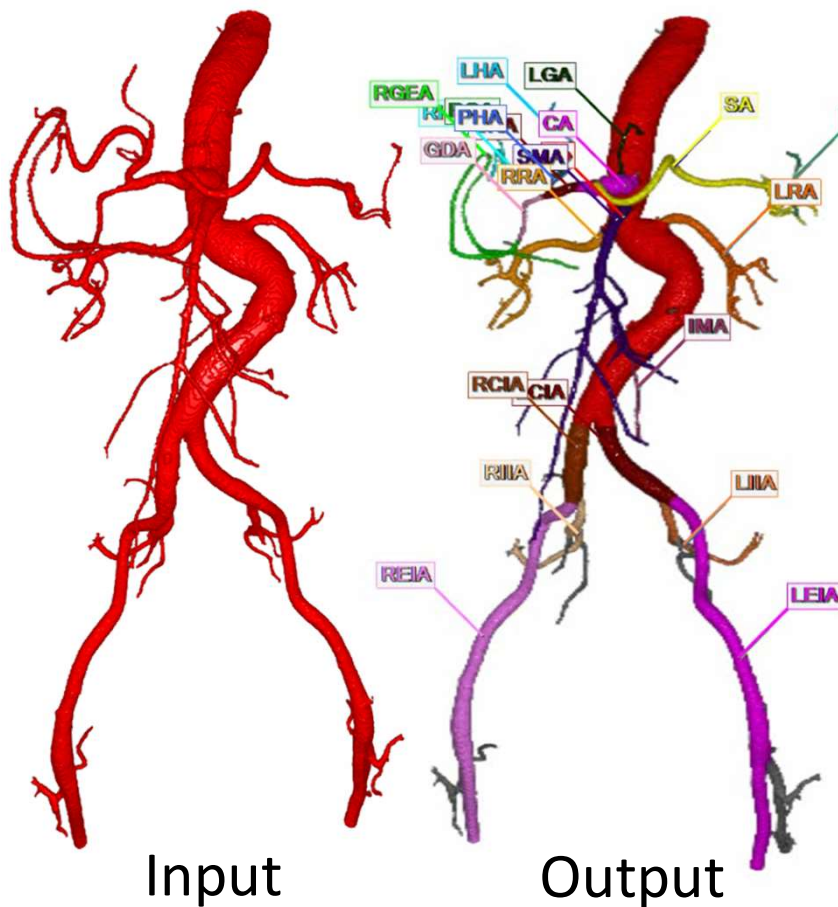
Training



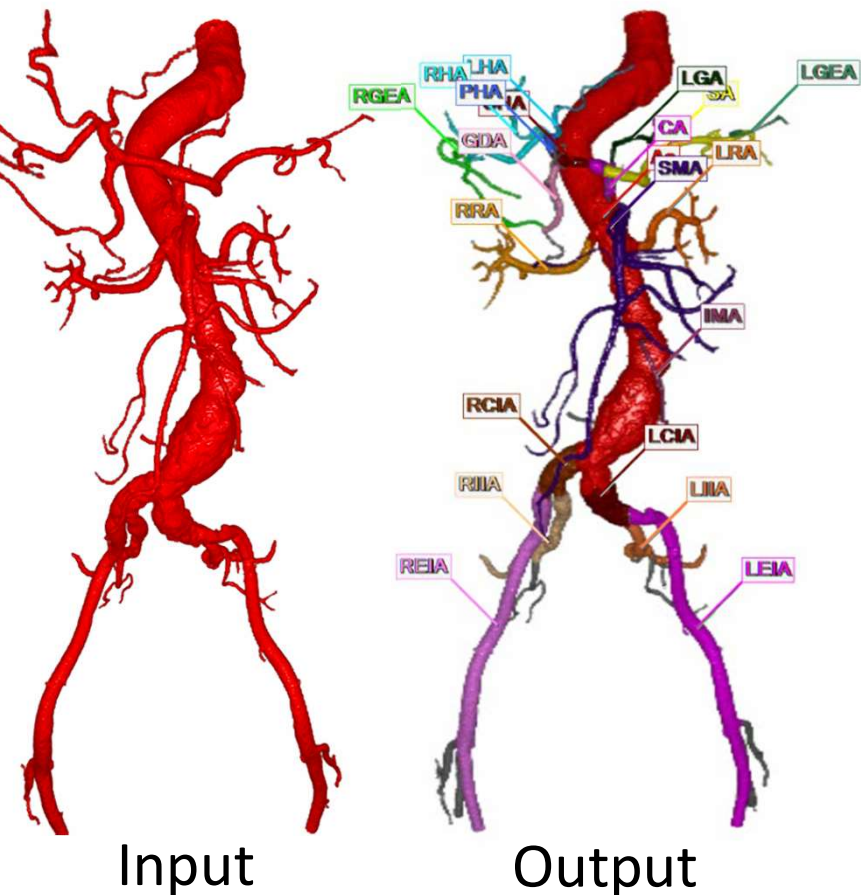
Testing



Results – Cases of 100% F-value

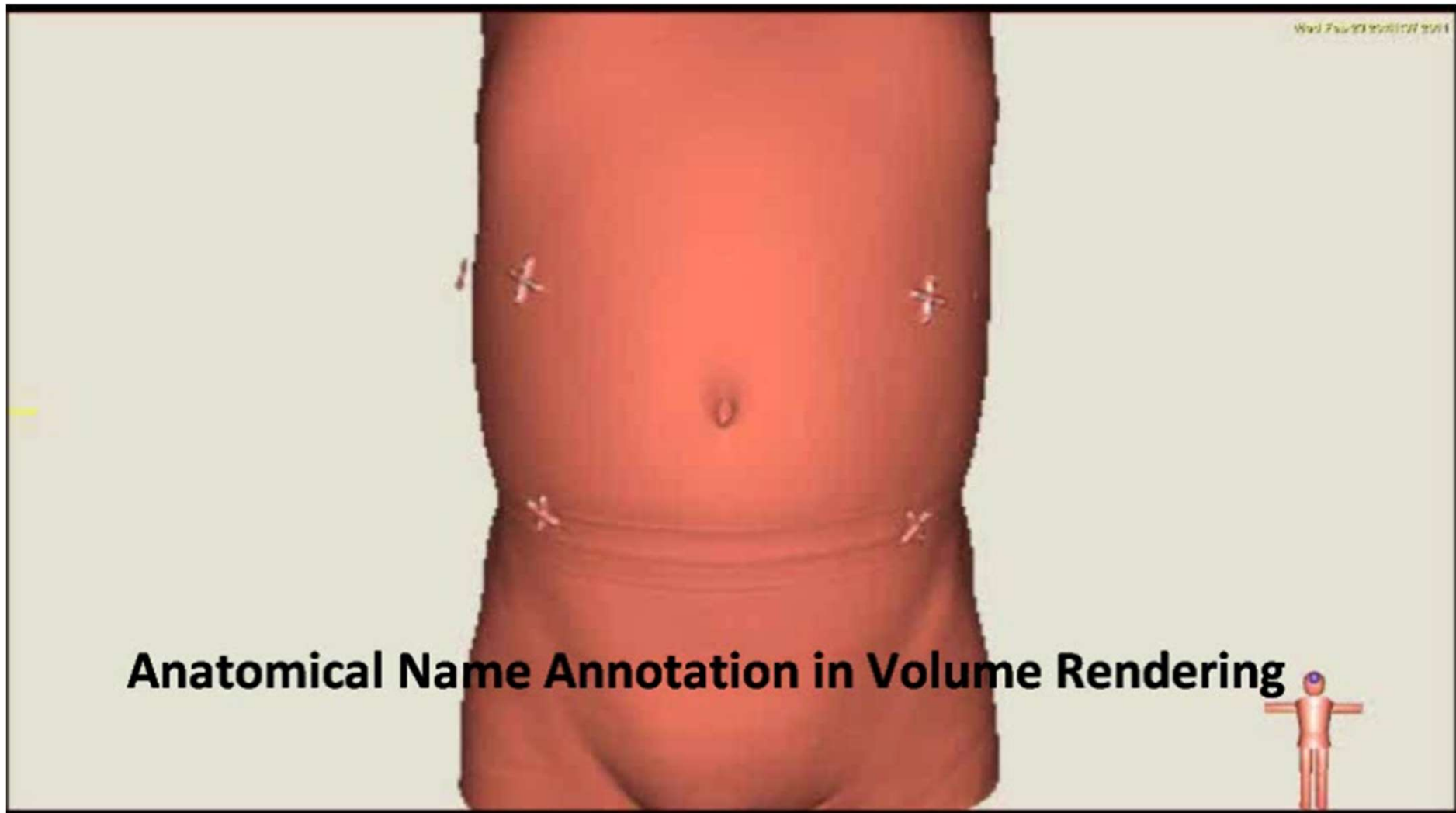


F-value 99.6%

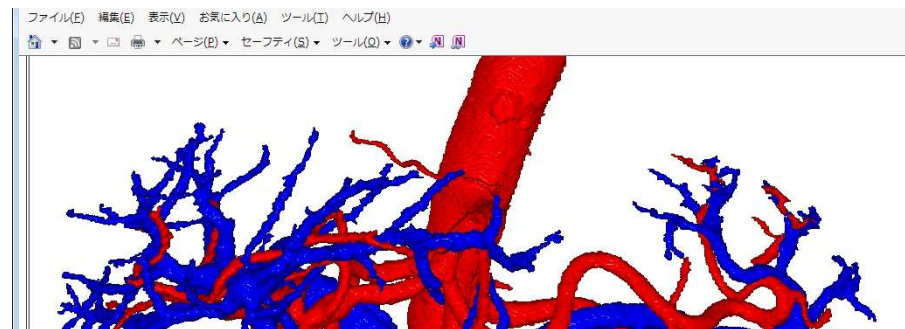


F-value 99.6%

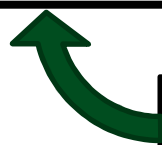
Anatomical name rendering on virtual anatomy



Branching structure reporting system



CHA	Bifurcate from the end of CHA
GDA	Bifurcate from the end of CHA
LGA	Bifurcate at 33.3mm point from the origin point of CA
RGA	Bifurcate at 22.1mm point from the origin point of GDA



RGA	Bifurcate at 22.1mm point from the origin point of GDA
LGEA	Bifurcate from the end of SA
RGEA	Bifurcate from the end of GDA
SA	Bifurcate from the end of CA
SMA	Bifurcate at 138.5mm point from the origin point of Ao
IMA	Bifurcate at 247.5mm point from the origin point of Ao
LRA	Bifurcate at 154.1mm point from the origin point of Ao



Oncological area

3D U-net for lymph node detection

Hirohisa Oda, Kanwal K. Bhatia, Holger R. Roth,
Masahiro Oda, Takayuki Kitasaka, Shingo Iwano,
Hirotoishi Homma, Hirotsugu Takabatake, Masaki Mori,
Hiroshi Natori, Julia A. Schnabel, Kensaku Mori



Accepted for SPIE Medical Imaging 2018

Mediastinal lymph nodes

- Lung cancer
 - Most common cause of cancer death
 - 1.69 million deaths worldwide in 2015
 - Treatment strategy depends on image diagnosis of lymph nodes
 - Image diagnosis of lymph nodes on chest CT volumes is a hard work for radiologists
- Automated mediastinal lymph node detection is desired
 - prevent overlooking of lymph nodes
 - 3D U-net based segmentation

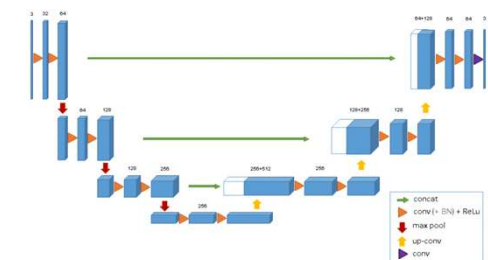
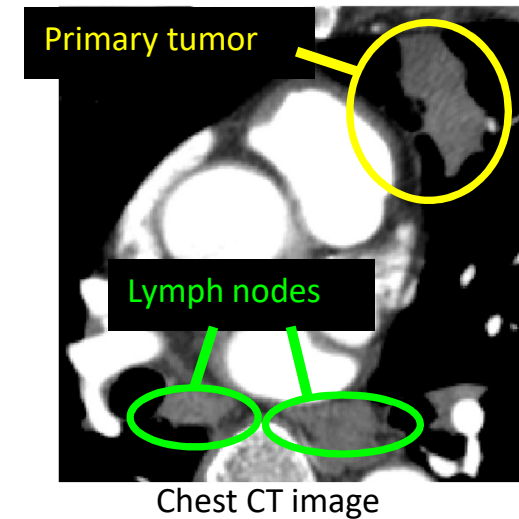
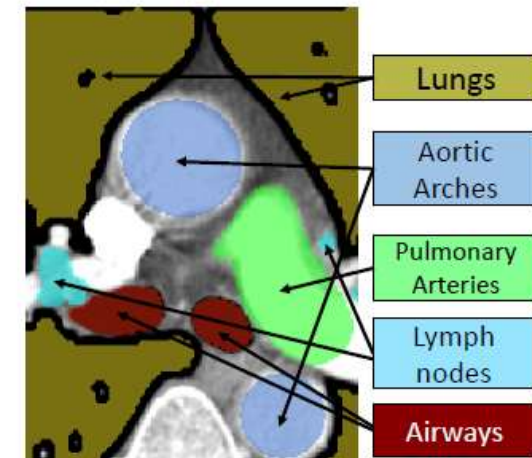


Fig.2 from [Cicek16]

Using surrounding anatomies

- Several anatomies around mediastinum
 - Lung, airways, aorta, and pulmonary artery
 - Easily segmented by thresholding, circle fitting, etc.
- Weighting regarding size of each class
 - Smaller class should have larger weight for training
 - Especially lymph nodes are much small regions than organs or major blood vessels

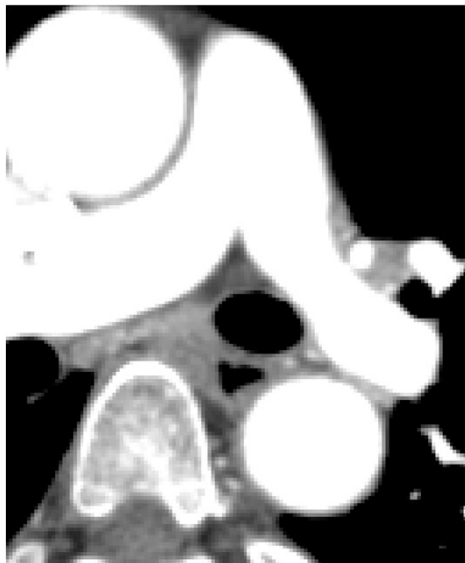


$$\mathcal{L} = -\frac{1}{N} \sum_{i=1}^K \lambda_i \left(\sum_{x \in N_i} \log(\hat{p}_k(\mathbf{x})) \right)$$

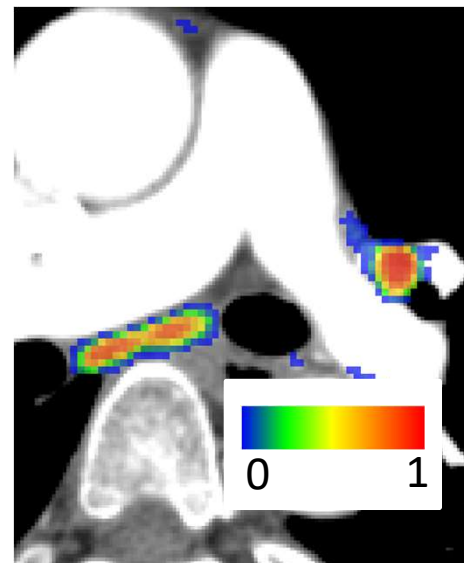
$$\lambda_i = \frac{1 - N_i/N_C}{K - 1}$$

Examples

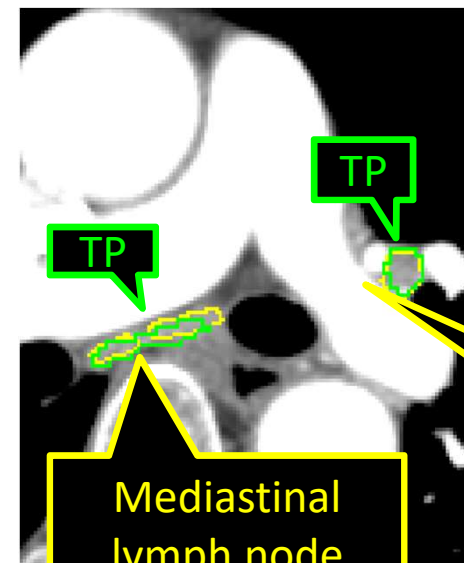
- Lymph nodes were properly detected
 - Segmentation accuracy also looks good



Input volume



Lymph node probabilities



Detection results ($t = 0.5$)

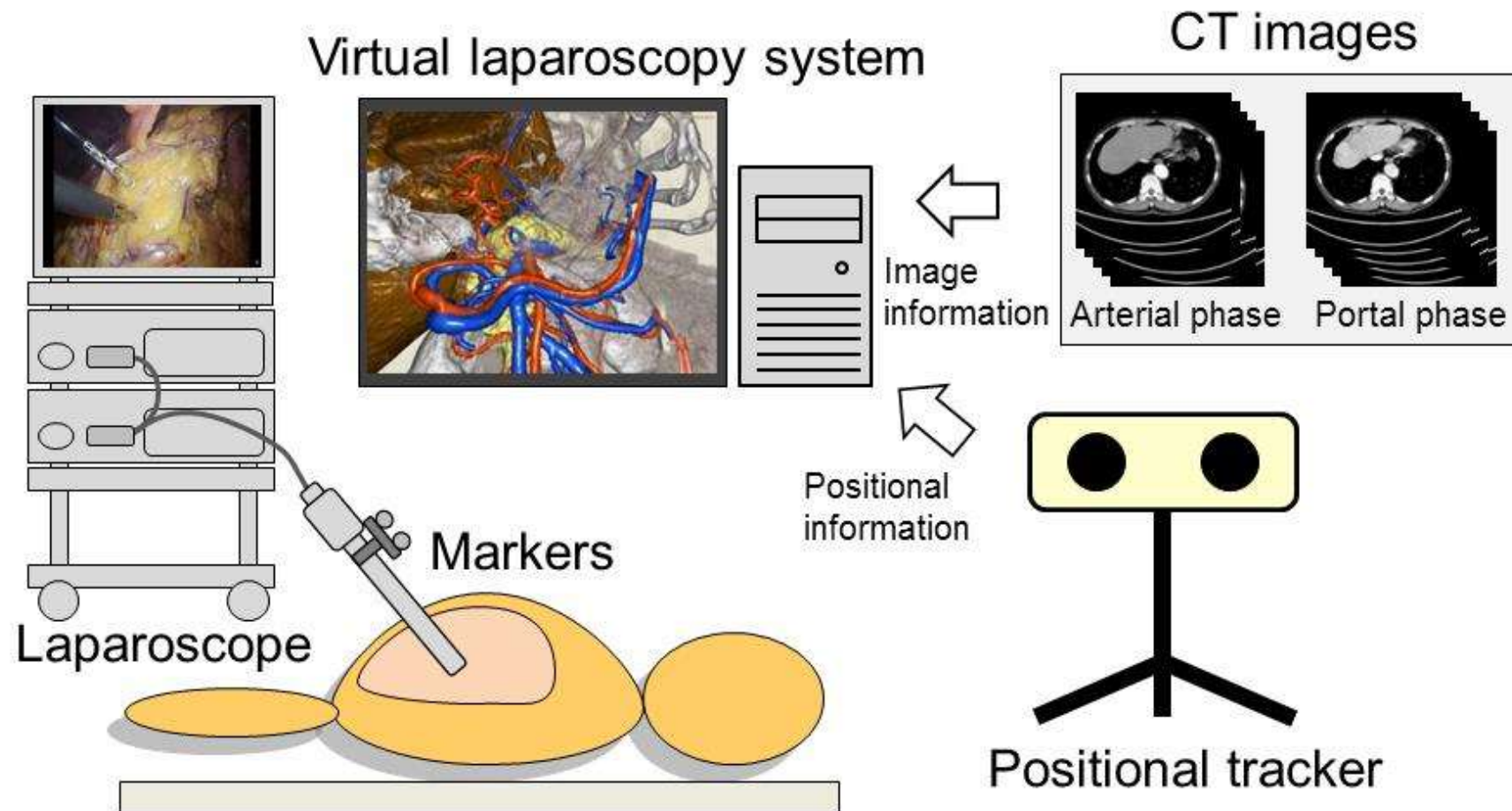
Mediastinal
lymph node

Hilar
lymph node



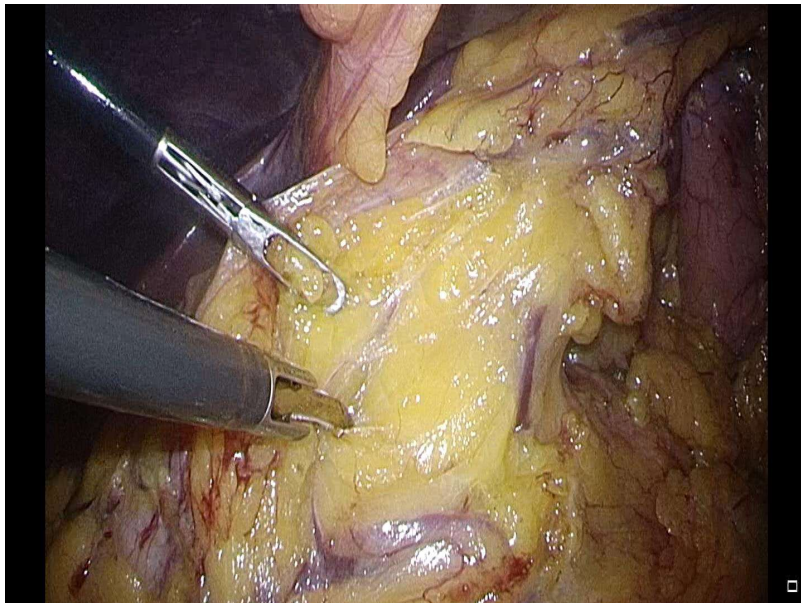
AI goes to operating theater

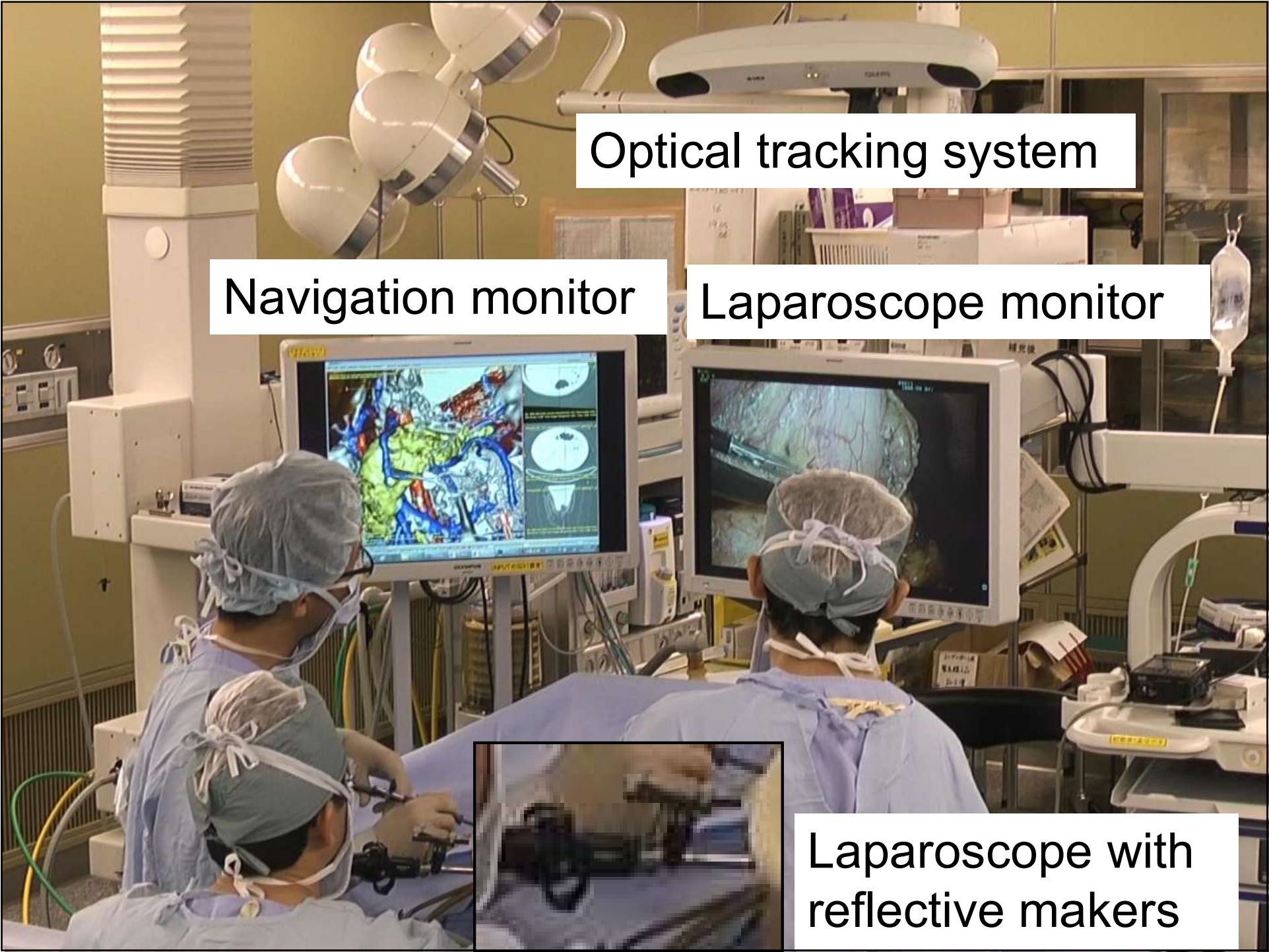
Laparoscopic surgery navigation



Surgical navigation of gastrectomy [Hayashi IJCARS2015]

- Comprehension of anatomical structure is important in laparoscopic surgery.
- 3D virtual laparoscopic views (3D VLVs) generated from preoperative CT images help surgeons to understand patients' anatomical structures.



A photograph of an operating room setup for laparoscopic surgery. Three surgeons in blue scrubs and masks are positioned around a patient. Two large monitors are visible: one on the left showing a 3D anatomical model with colored vessels, and one on the right showing a live laparoscopic video feed. An optical tracking system is mounted on a stand above the monitors. A text label 'Optical tracking system' points to this device. Another text label 'Navigation monitor' points to the left monitor. A third text label 'Laparoscope monitor' points to the right monitor. In the bottom center, there is an inset image showing a close-up of a laparoscope with reflective markers attached to its handle. A text label 'Laparoscope with reflective markers' points to this inset. The background shows typical operating room equipment like lights and storage units.

Optical tracking system

Navigation monitor

Laparoscope monitor

A close-up inset image showing a laparoscope. Several small, dark, reflective markers are attached to the handle of the instrument. A text label 'Laparoscope with reflective markers' points to this inset.

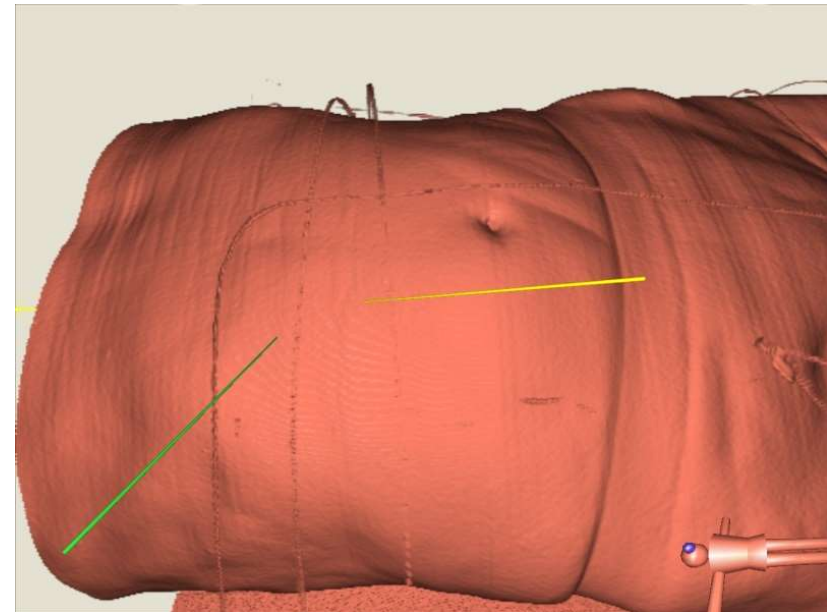
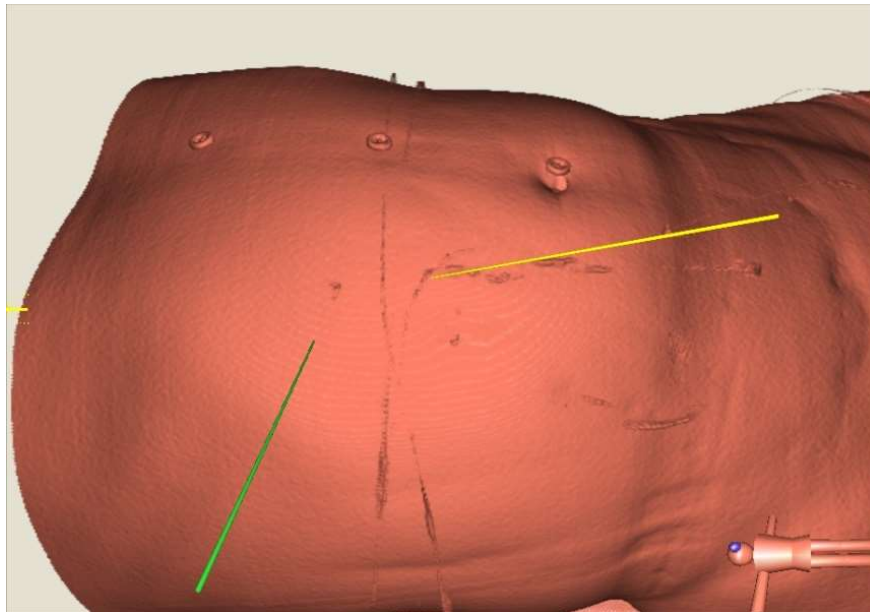
Laparoscope with reflective markers

Laparoscopic gastrectomy navigation



Purpose

- Port (trocar) location planning system
 - Determine port location based on anatomical structure
 - RGA and LGA

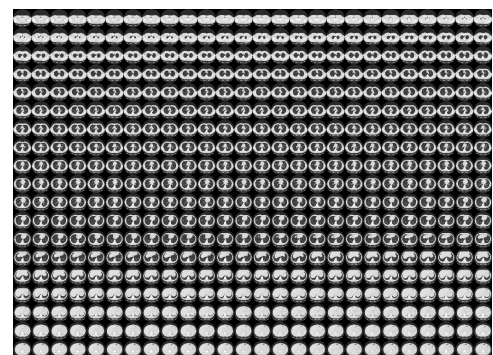




VR

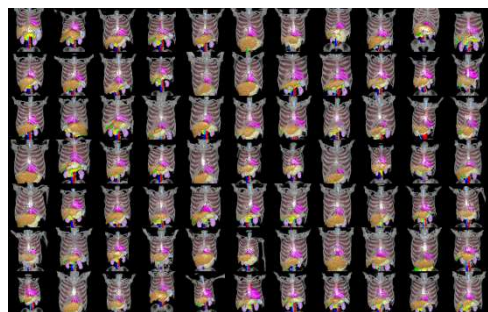
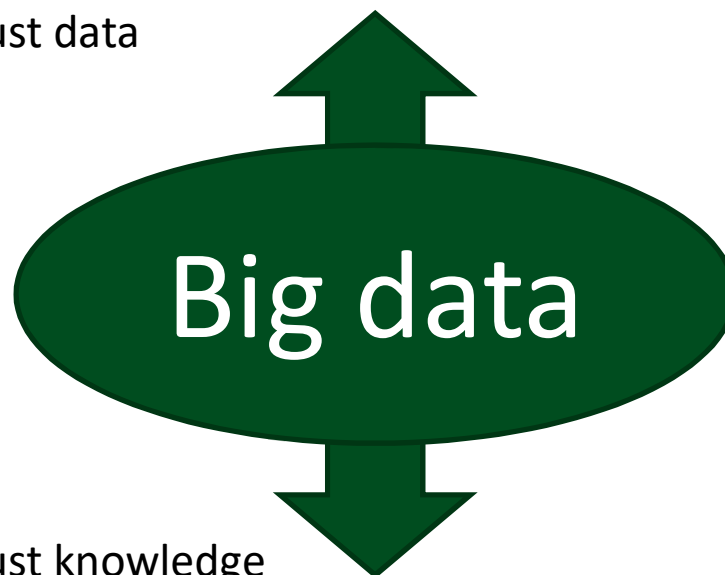


Easy to obtain, not suitable for supervised learning



Raw big data

Just data



Just knowledge

Annotated big data

How to bridge the gap!
How to convert!

Good for supervised learning, but very hard to collect



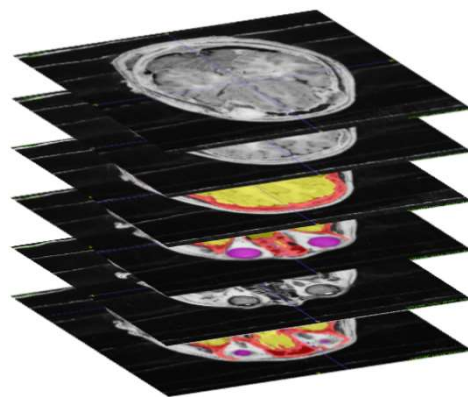
Biomedical big data

Many cases, large data per case

Many cases, small data per case

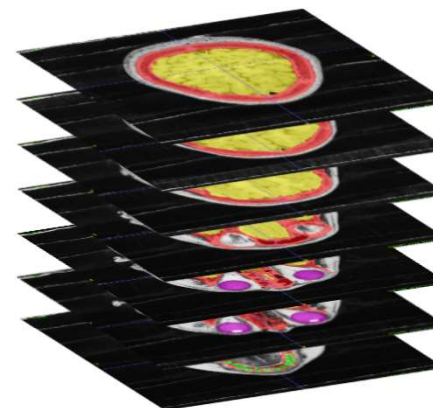
Small cases, huge data per case

From sparse annotation to full annotation



Sparse annotation

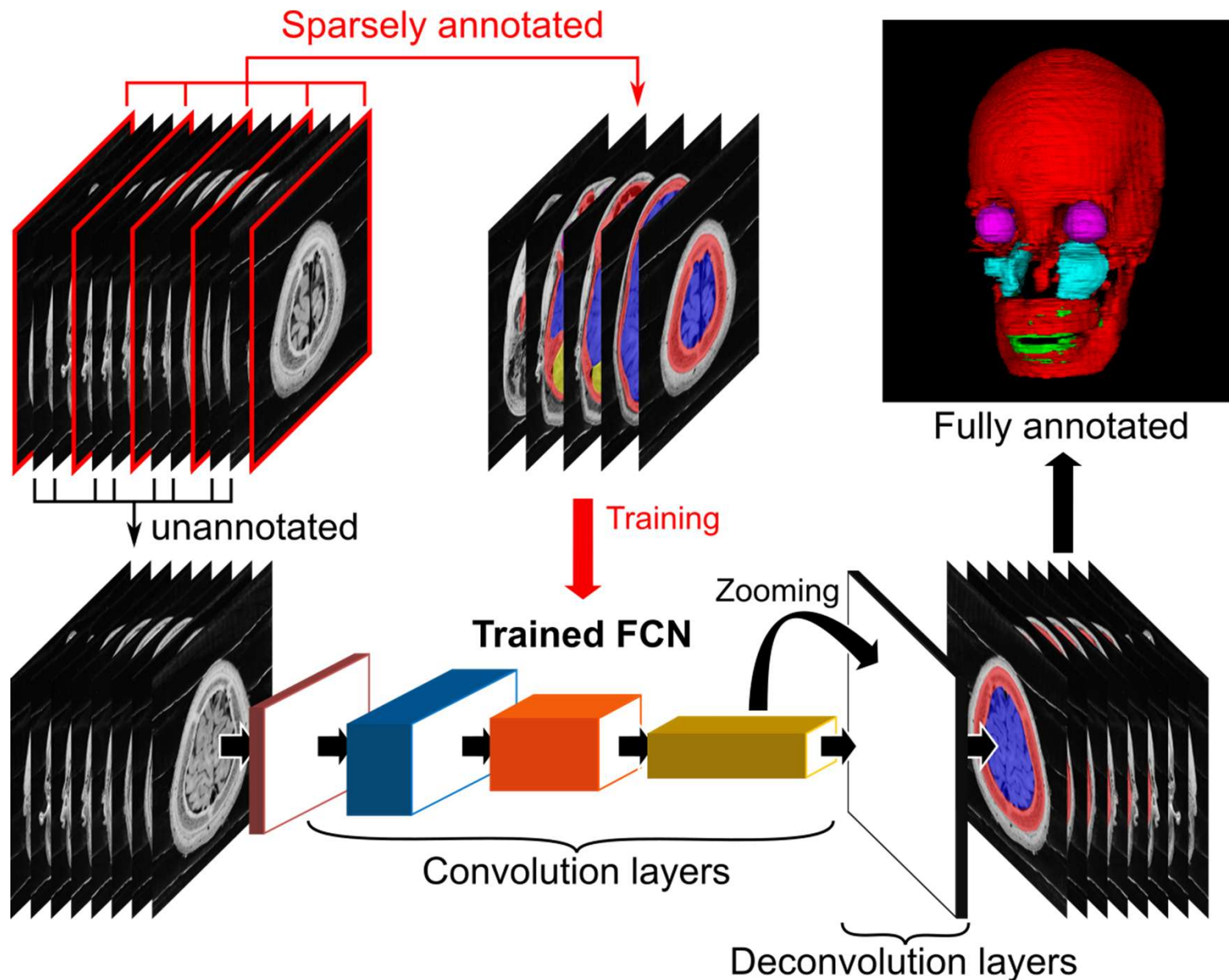
unannotated
unannotated
annotated
annotated
unannotated
annotated



Full annotation

annotated
annotated
annotated
annotated
annotated
annotated

Segmentation based on sparse annotation



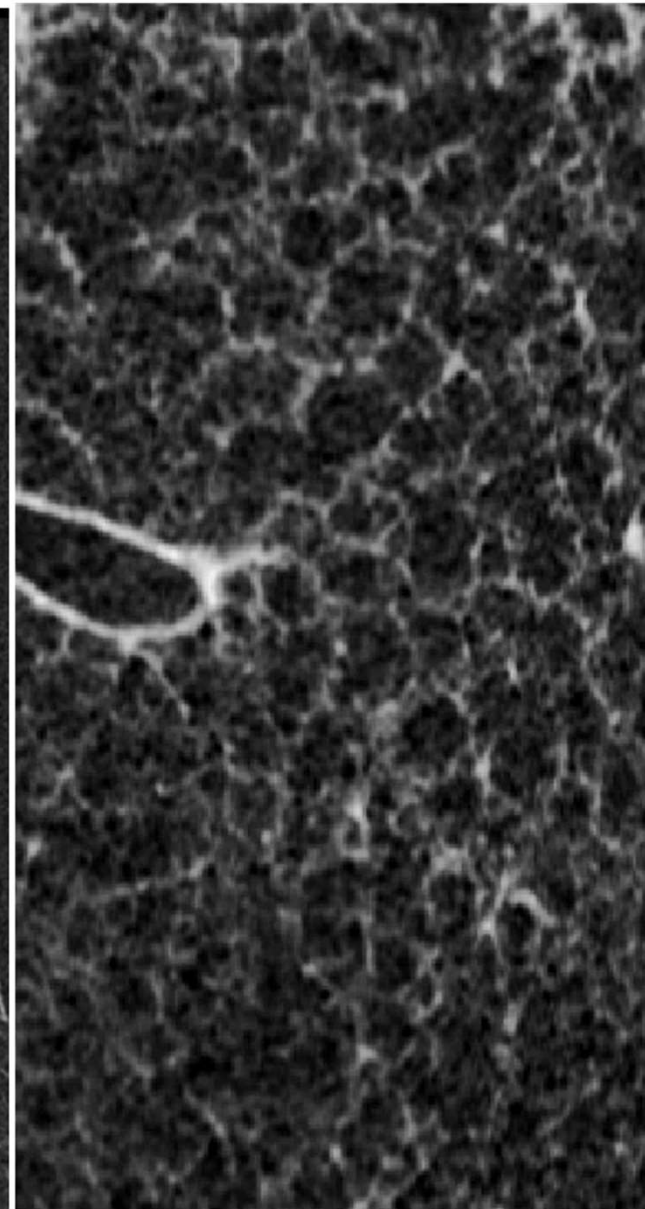
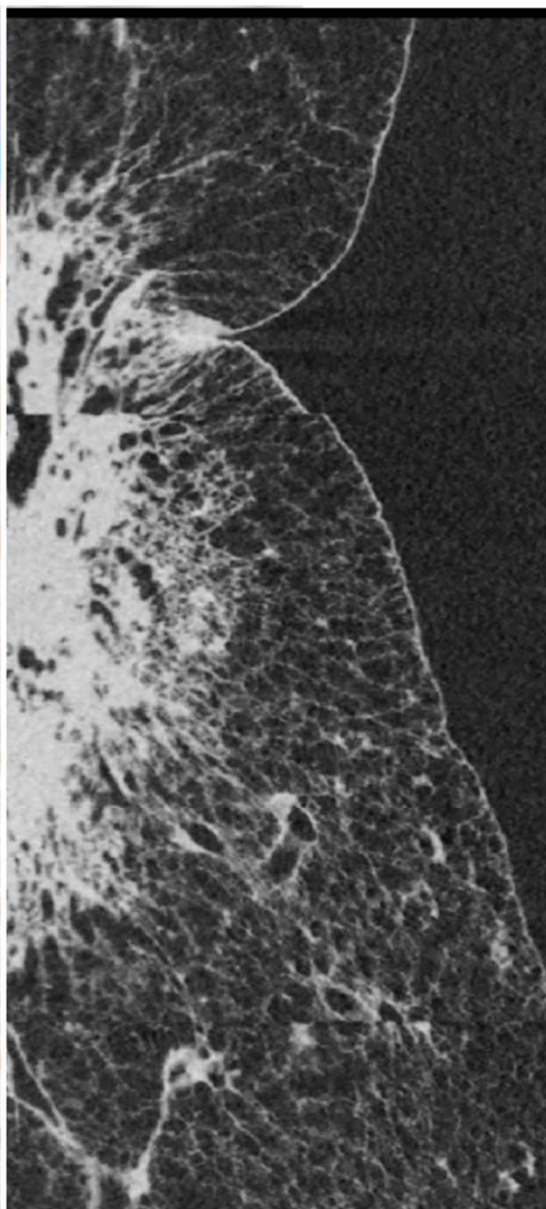
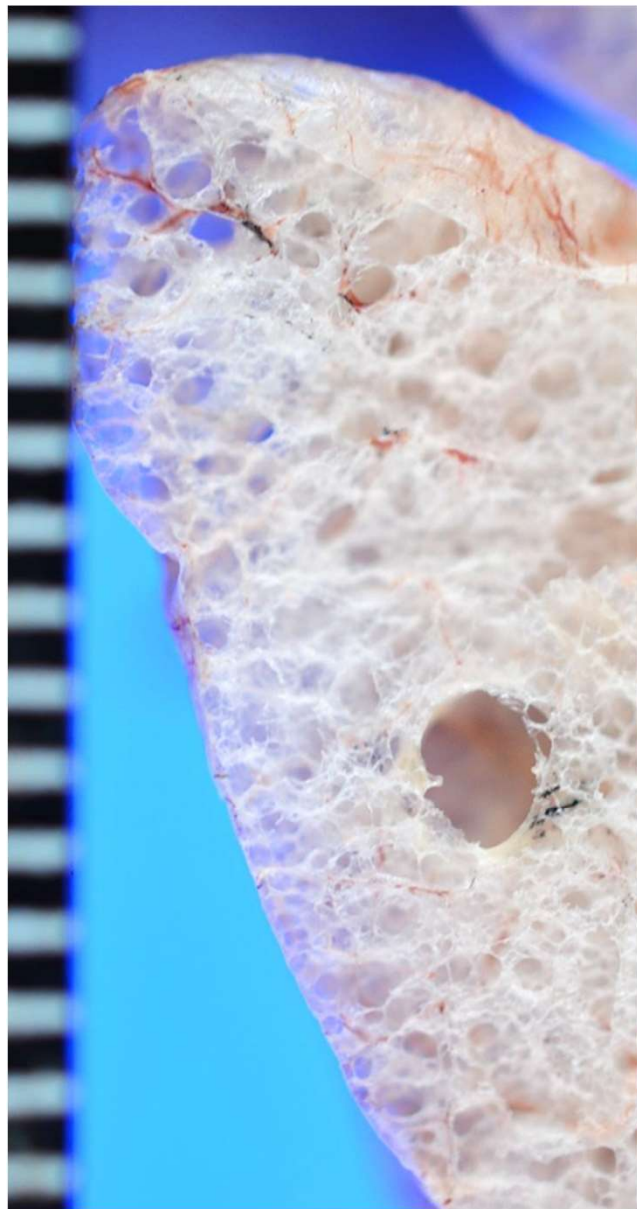
Lung specimen

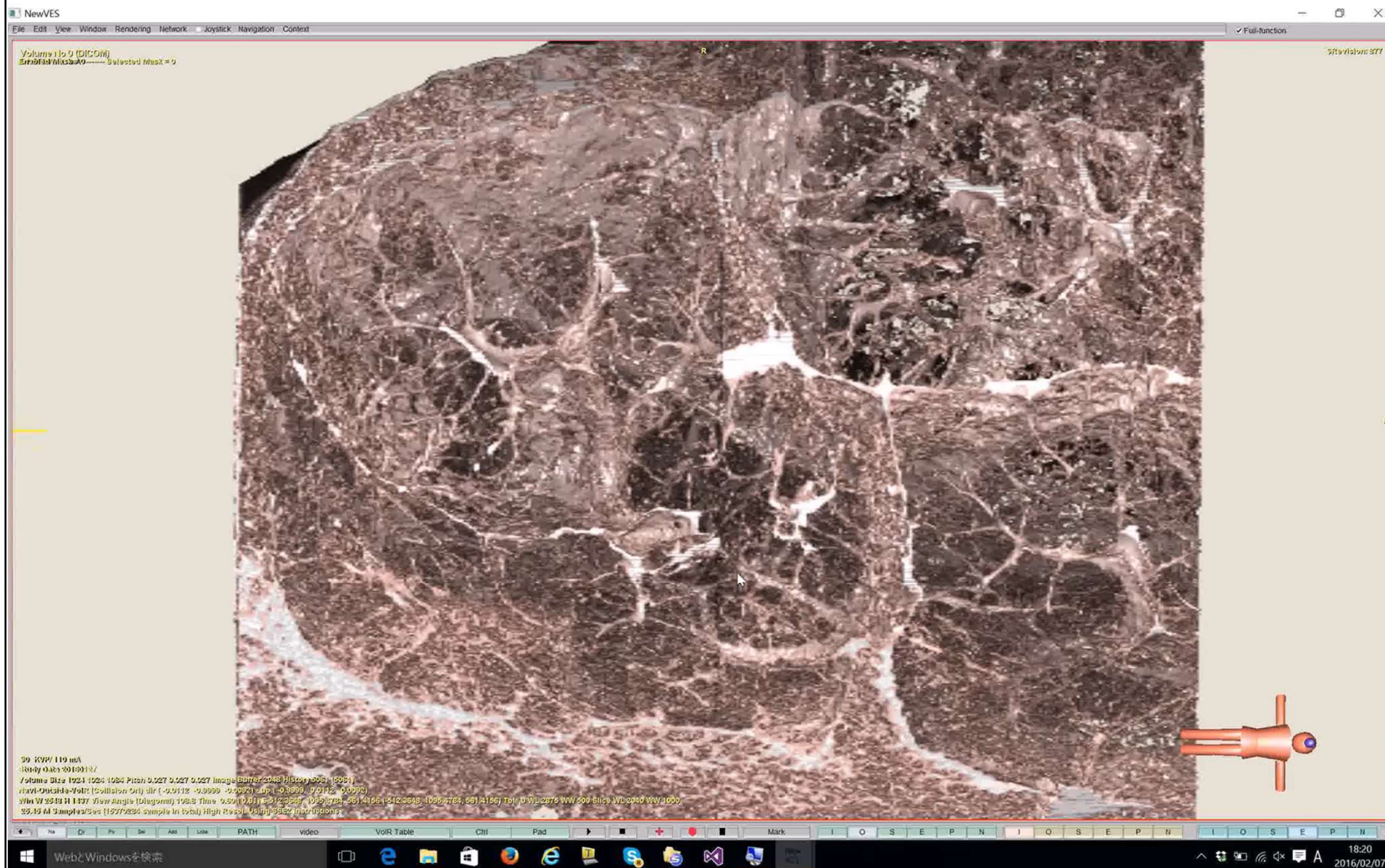


Inflated Fixed Lung Specimen

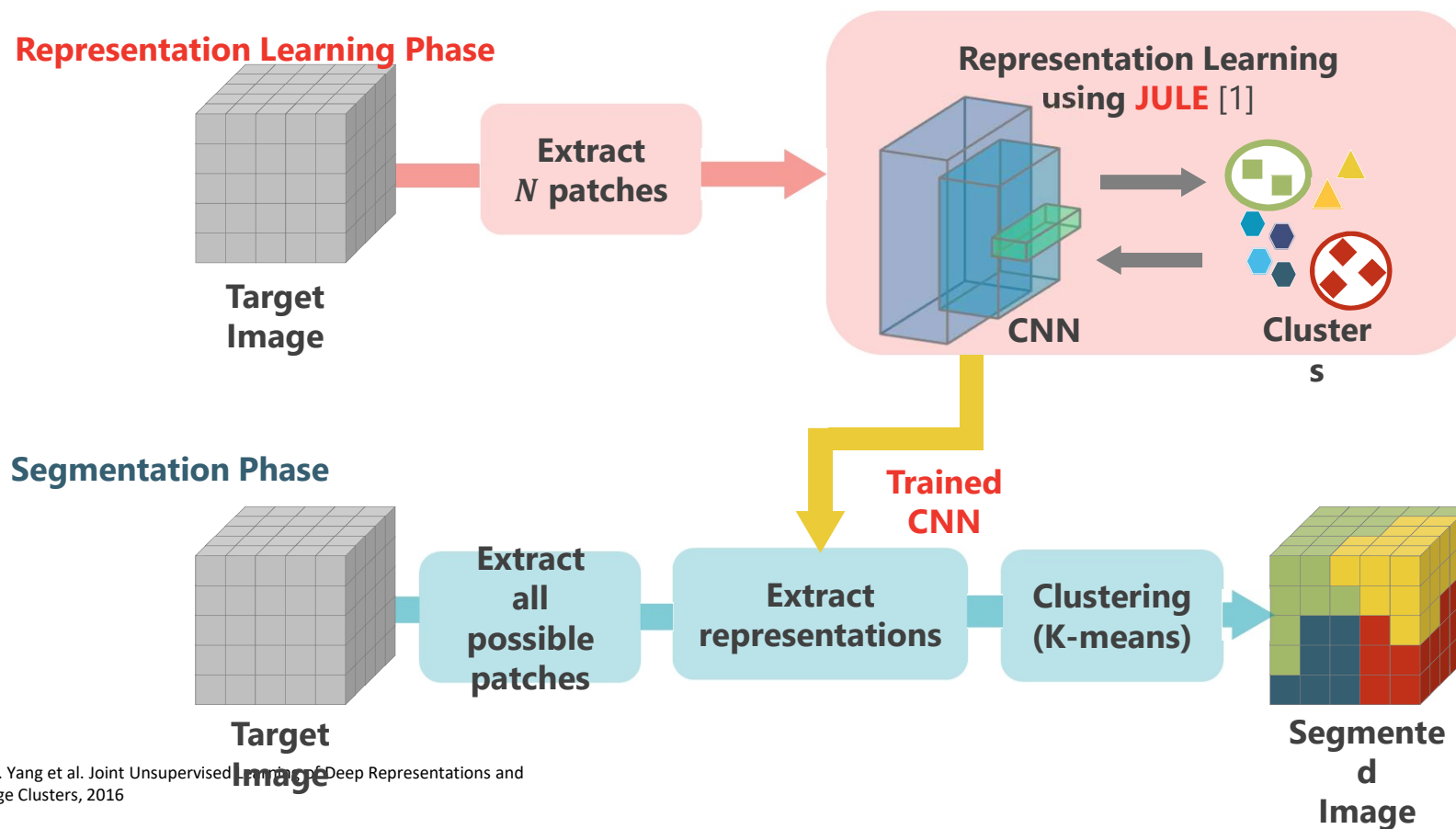
Micro CT scanner (up to 5um/voxel)





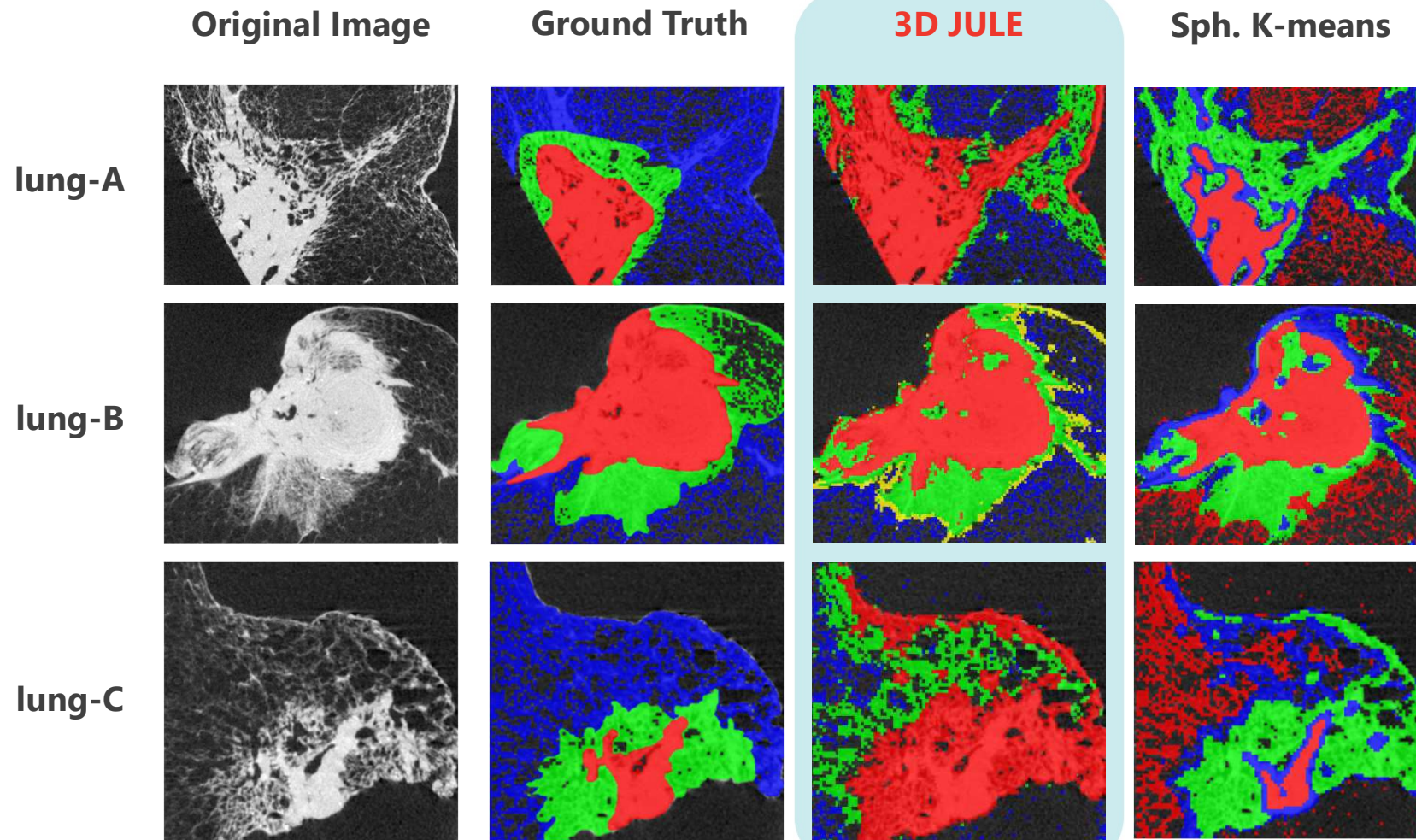


Unsupervised segmentation of uCT



[1] J. Yang et al. Joint Unsupervised Learning of Deep Representations and Image Clusters, 2016

Segmentation of uCT volume of lung cancer





**Medical images will be fully
annotated by computers**

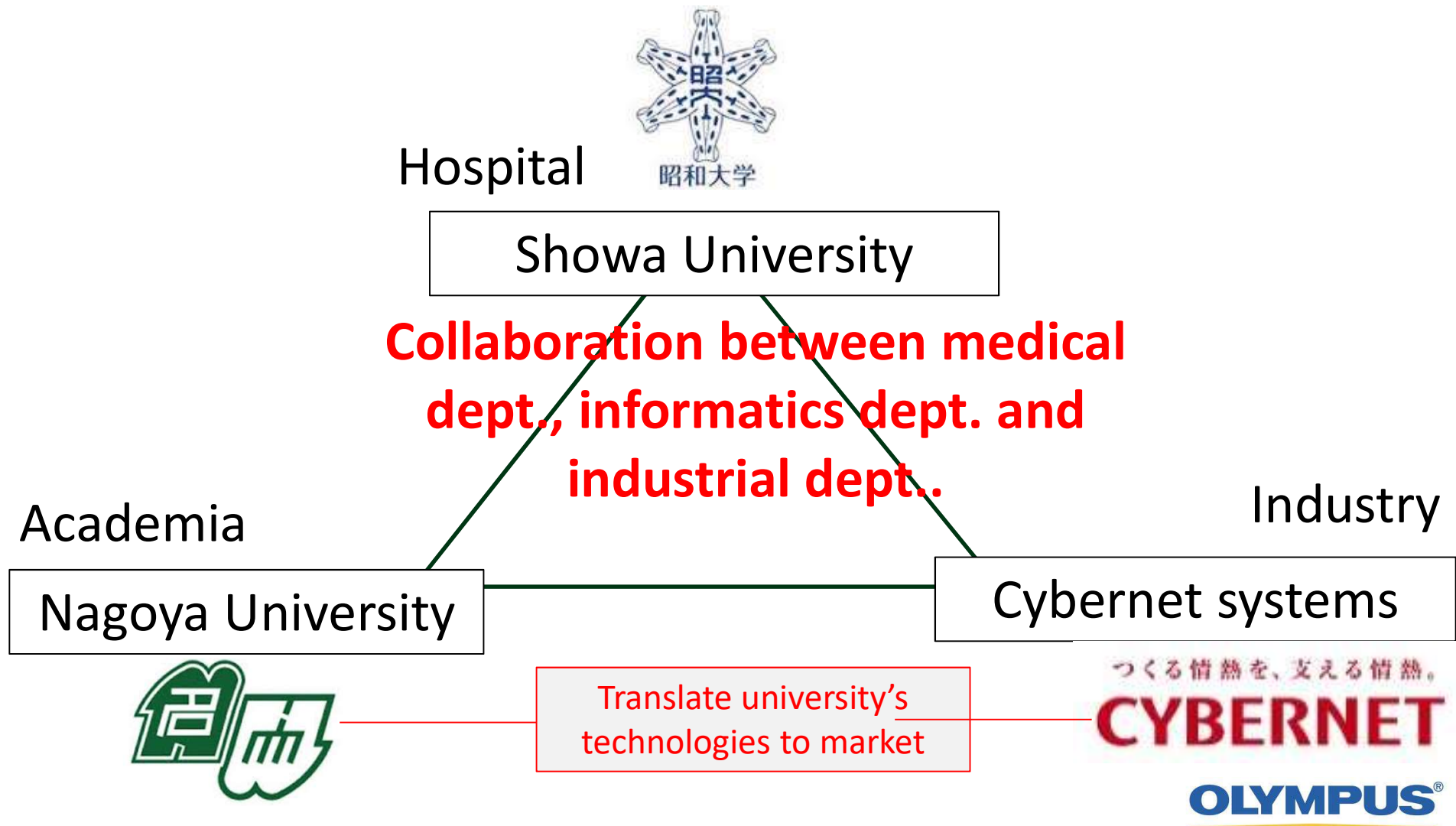
Future

- All of medical imaging data will be annotated by machine learning in future
- This already happens in digital photography area
 - Many cloud-based photo services automatically annotated photos by ML
- How does this change our medical world?
 - Medical doctor / Engineers / Patient
 - ML-based medicine comes home for monitoring daily health conditions?

Conclusions (and open questions)

- Machine learning (AI)
 - Medical image diagnosis
 - Computer assisted intervention
- ML will become indispensable technique in medicine
 - All of supportive tools will be based on ML
- How to integrate ML/AI into clinical workflow
 - c.f.) Surgeons refer surgical navigation in very short time during surgery. But it is very critical point.
- Big data and lack of supervised data
 - Data is a lot but not structured or not annotated
 - Unsupervised learning and weak annotation will be a key
 - How to create big supervised data from small supervised data from big data.

Academia, hospital and industry



Conclusions (and open questions)

- Current medical AI is very specific
 - Good performance in specific tasks
 - Lack of observation of real patients
- Ethics in medical AI
 - Personal information used for training
 - Personal information protection law in Japan
 - Clear distinction of **academic** research use and **industrial** use
 - Overriding medical doctors' decisions
- Cross-border data collection for medical AI
 - Raw data
 - Labeled data
 - Data circulation



Conclusions (and open questions)

- AI is currently led by IT giants
 - Collecting data so much
 - 1984 (George Orwell)?